

Personal Recognition Based on Facial Information

Research (in biometrics) at Halmstad University, Sweden



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Content

- About Halmstad University
- Biometrics Research at Halmstad University
- Fingerprints, lip-motion
- Iris Analysis
- Periocular Analysis
- Face Analysis



About Halmstad University

School of Information Science Computer and Electrical Engineering

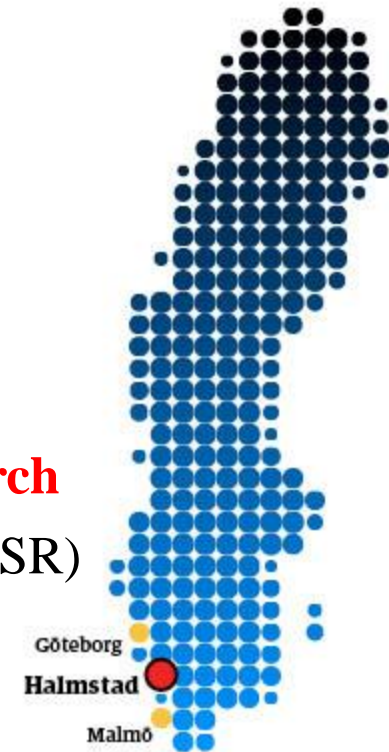
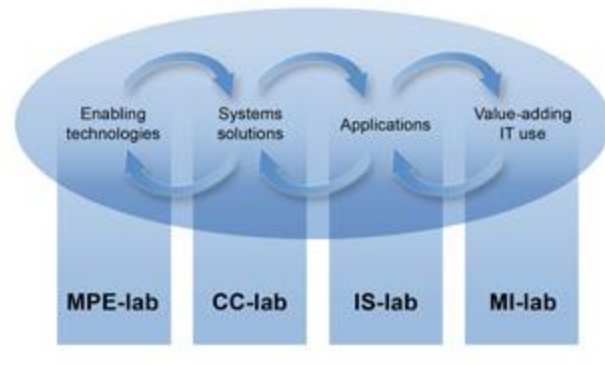
Largest research environment at Halmstad University

85 people from 20 nationalities

Organized in 4 different laboratories:

- **Computing and Communication** (CC-lab)
- **Man and Information technology** (MI-lab)
- **Mathematics, Physics and Electrical engineering** (MPE-lab)
- **Intelligent Systems / Centre for Applied Intelligent Systems Research**

(IS-lab/CAISR)



About Halmstad University

Intelligent Systems laboratory (IS-lab/CAISR)

Research areas

Signal analysis

Mechatronics

Machine learning

IS-lab
CAISR

Application areas

Intelligent
vehicles

Health
technology

Biometrics



Biometrics Research

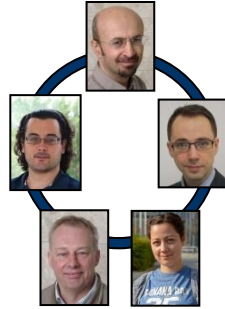
Well-recognized group in Sweden, with international impact

With funding from:

- **Swedish Research Council** (postdoctoral grant, project grants)
- **EU FP6/FP7**
 - Marie Curie Intra-European Fellowship (2011-2013)
 - BIOSECURE Network of Excellence (2004-2007)
 - BBfor2 Marie Curie Initial Training Network (2010-2014)
- **EU COST Actions** IC1106 and 275

And research in topics including:

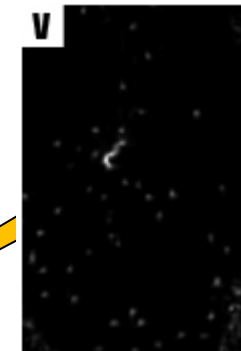
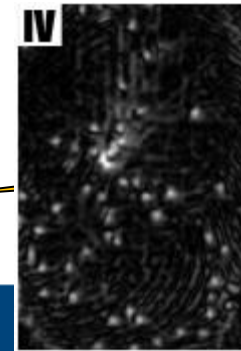
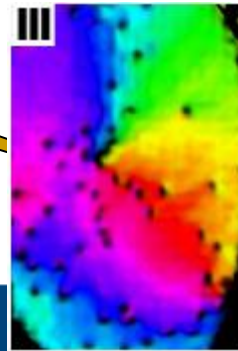
- Fingerprints, iris, face, lip-motion
- Quality analysis
- Multibiometrics
- Liveness detection



Fingerprints

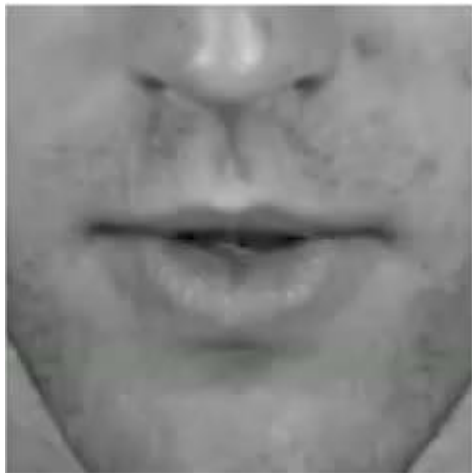
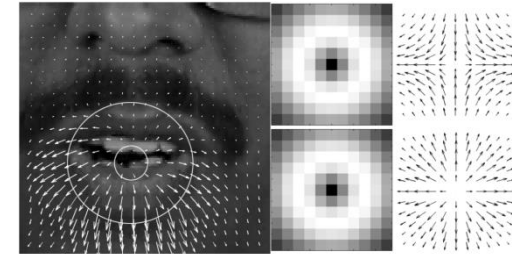
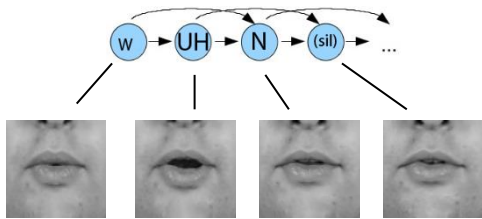


- Image **quality** estimation and enhancement
- Orientation** extraction
- Detection of “prominent” **points**
- Identity** by fingerprints
- Forensics** analysis

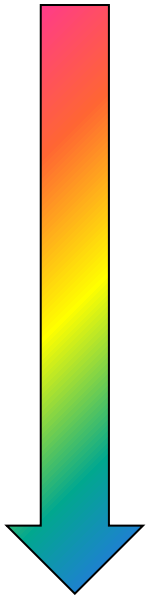


Lip Motion Analysis

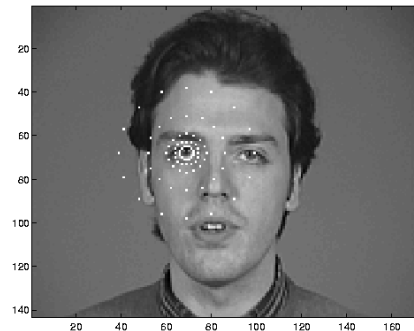
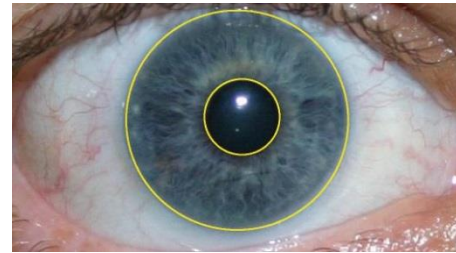
- Lip-motion dynamics
- Use:
 - Person recognition
 - Liveness assessment
 - Lip-reading, speech analysis
 - Avatar emulation (face synthesis)



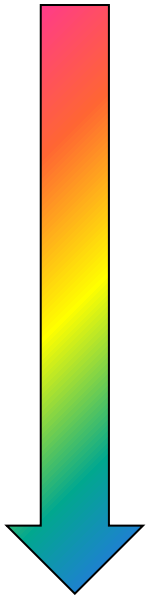
Personal Recognition based on Facial Information



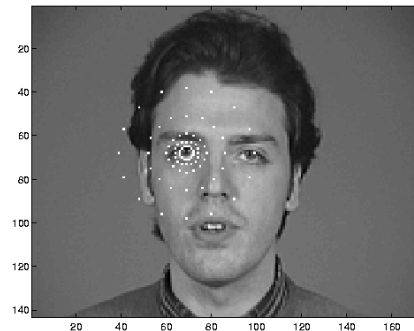
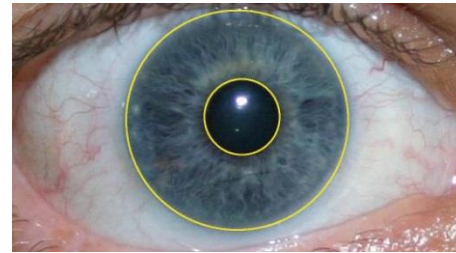
- **Iris Analysis**
- **Periocular Analysis**
- **Face Analysis**



Personal Recognition based on Facial Information

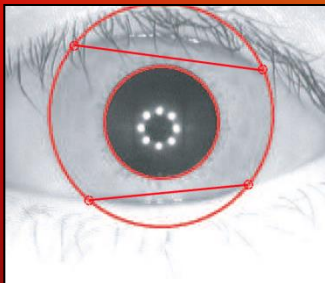
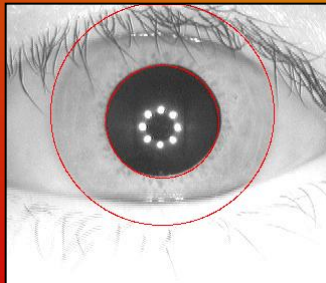
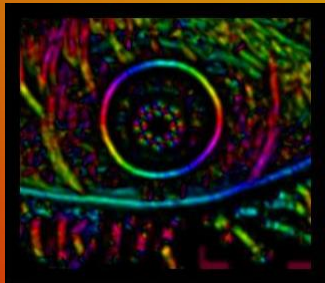
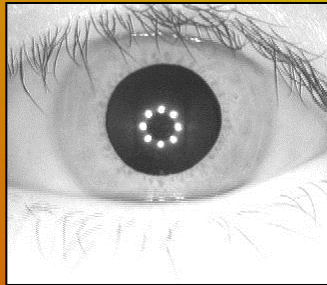


- **Iris Analysis**
- Periocular Analysis
- Face Analysis

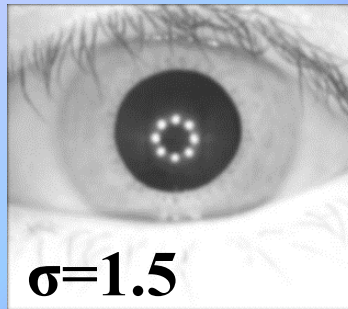


Iris Analysis

- ❑ Iris **detection** and **segmentation**
- ❑ Image **quality** analysis
- ❑ **Identity** by iris



defocus blur



Edge sharpness

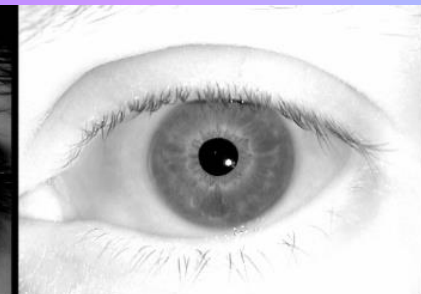


Pupil: 40.17
Sclera: 99.77

Gray level variability

high (0.78)

low (0.29)



Iris Segmentation using Symmetry Filters (GST)

Hue: direction
Saturation: magnitude

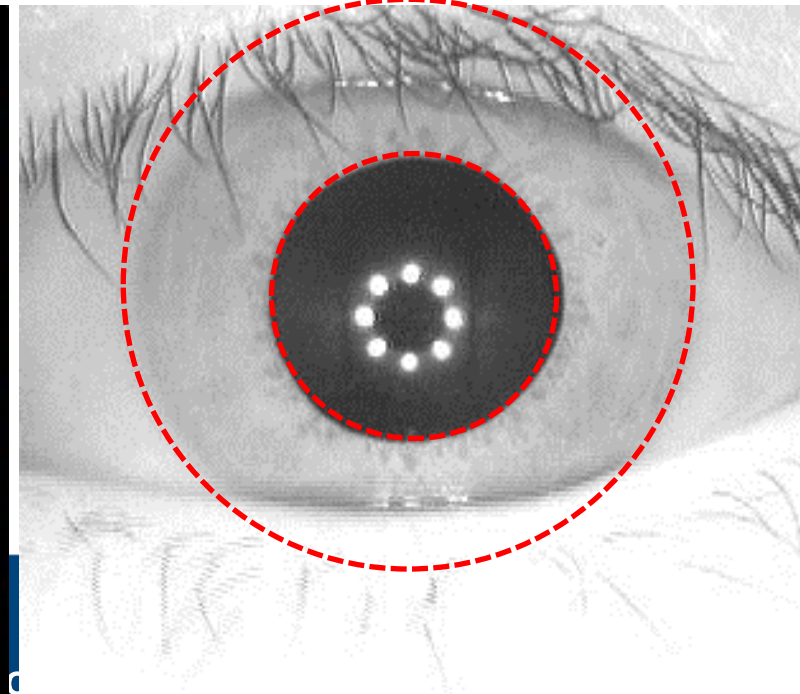
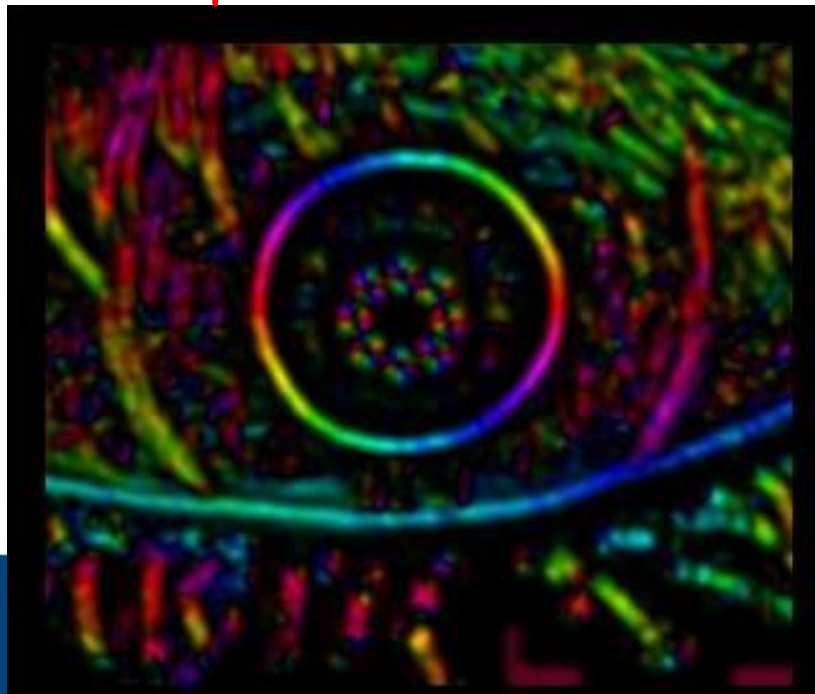
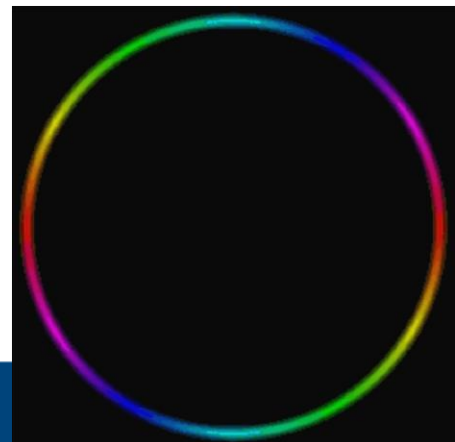
The Generalized Structure Tensor (GST)

- ❖ GST is a **feature matrix/vector** that can be represented by one complex, I_{20} , and one real valued, I_{11} , measurement:

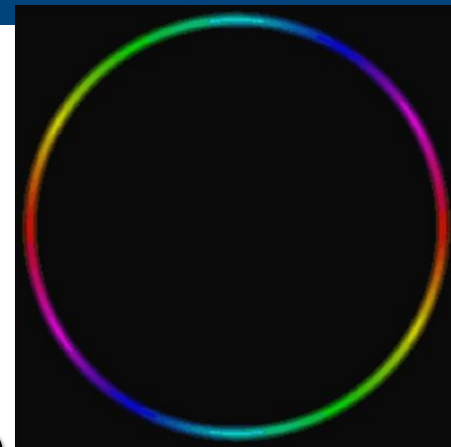
$$I_{20} = \sum_p c[p] (f_x[p] + if_y[p])^2$$

$$I_{11} = \sum_p |c[p]| |(f_x[p] + if_y[p])^2|$$

**(complex)
circular filter**



Iris Segmentation using the GST



The Generalized Structure Tensor (GST)

- ❖ The circular filter is an example of **symmetry filters**, designed to detect points with certain symmetry (circular, parabolic, linear...)
 - Magnitudes I_{20} and I_{11} encode the evidence of the sought symmetry

- Apart from **correlation of edge magnitudes**, the filter takes into account the **direction of edges** (by encoding its expected orientation), so any disagreement in the direction will be penalized
 - ❑ Not exploited by other edge-based methods (Daugman, Wildes)



All boundary pixels contribute equally (**do not penalize**) the detection of circles

Detection Tasks Using Symmetry Filters

Symmetry filters: family of filters (computed from symmetry derivatives of Gaussians) to detect **position and orientation of symmetric patterns** such as lines, circles, parabolas, stars...

- For each family of symmetric patterns, there is an **appropriate symmetry filter** suitable to detect the **whole family**
- The maximum in the filter response (magnitude of I_{20}) gives **evidence** of the sought symmetry pattern, and the argument of I_{20} at maxima locations gives the

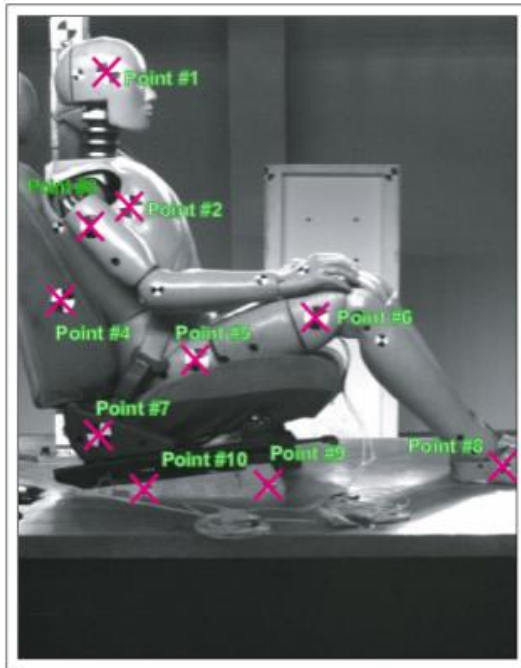
Orientation	$g(z) = \log(z)$	$g(z) = z^{-1}$	$g(z) = z^{1/2}$	$g(z) = z$	$g(z) = z^2$
2π					
π					
$2\pi/3$					
$4\pi/3$					

orientation
of the pattern

Detection Tasks Using Symmetry Filters

Symmetry filters have been successfully applied to a wide range of detection tasks

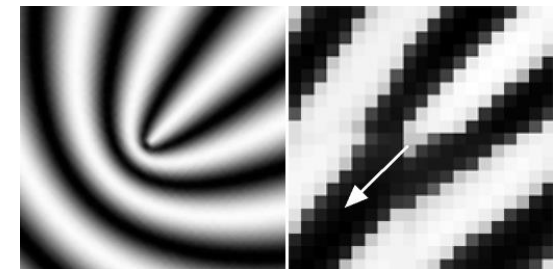
crash test



robot tracking



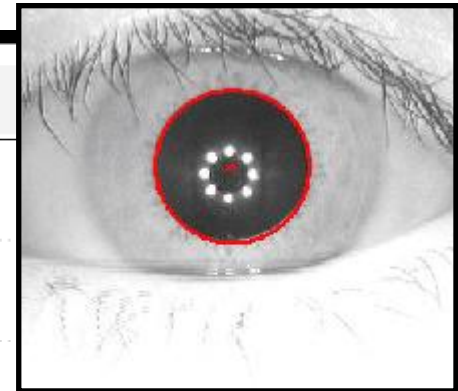
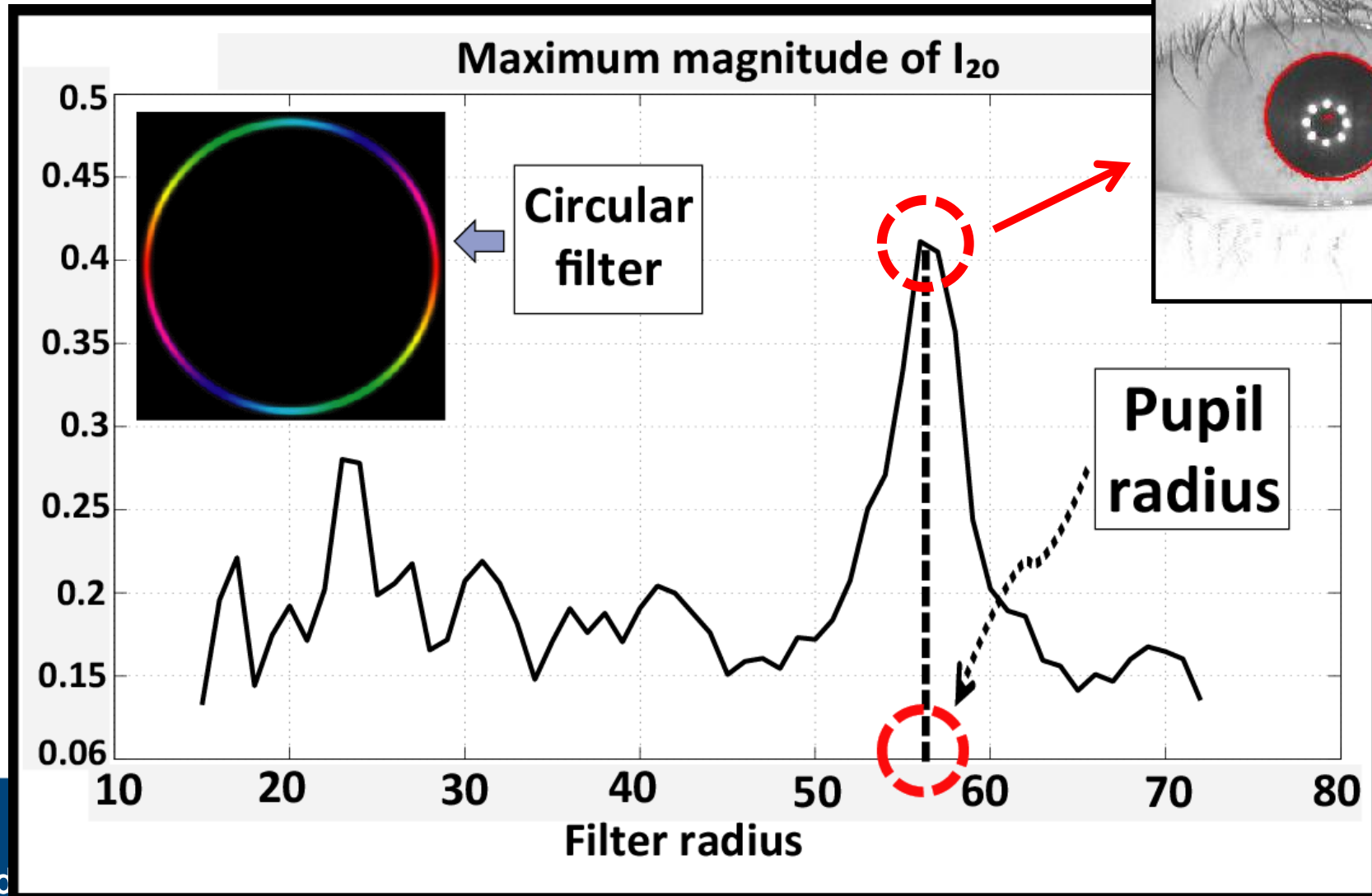
Fingerprint minutiae



Iris Segmentation using the GST

$$I_{20} = cf * \left(\frac{\partial I}{\partial x} + i \frac{\partial I}{\partial y} \right)^2$$

Finding the inner iris boundary

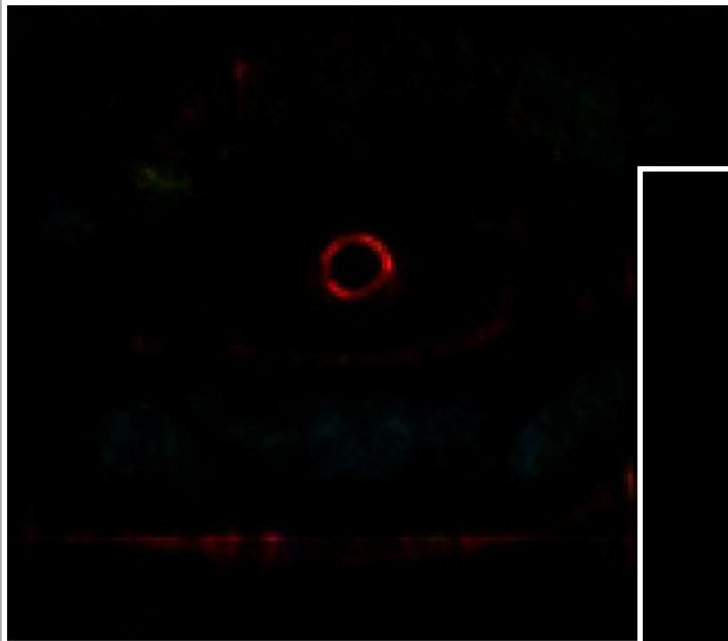


Iris Segmentation using the GST

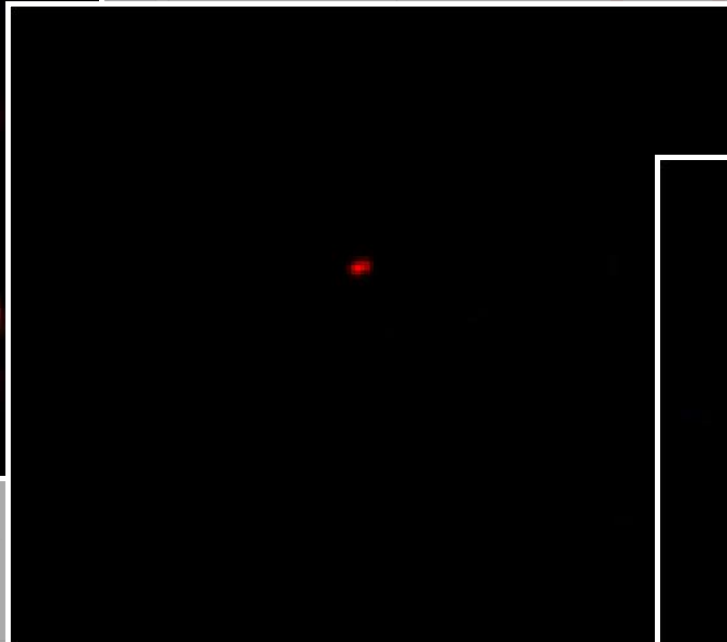
$$I_{20} = cf * \left(\frac{\partial I}{\partial x} + i \frac{\partial I}{\partial y} \right)^2$$

How filter output looks like with different filter radius...

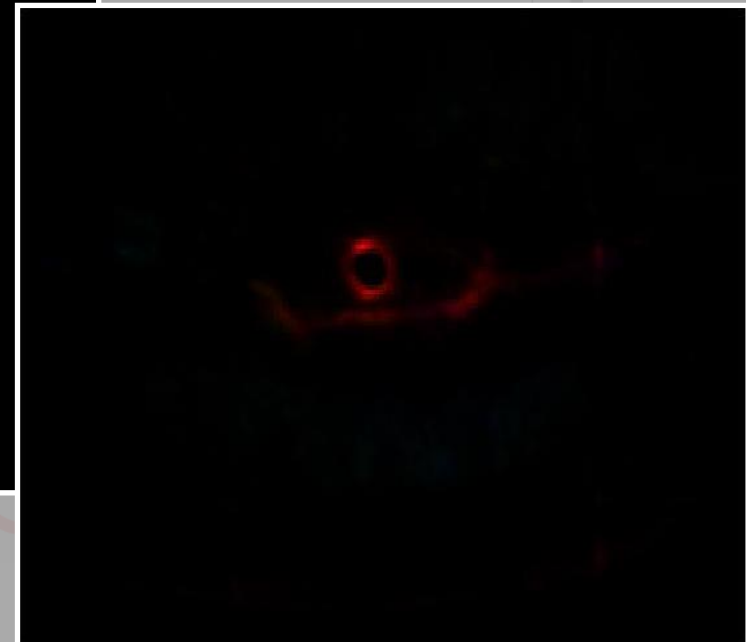
radius=45



radius=55



radius=65



0.15

0.06

10

20

30

40

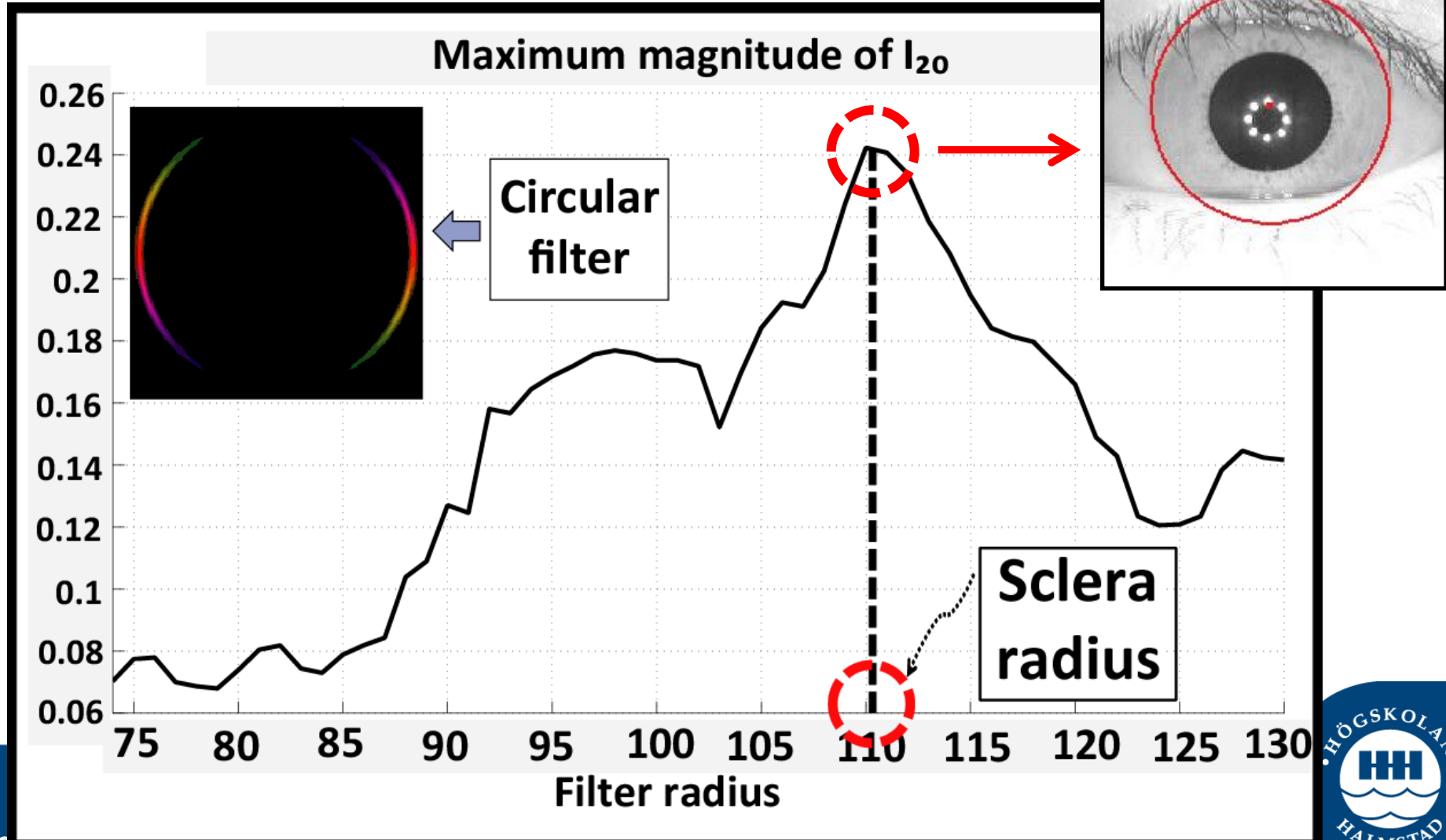
50

Filter radius

Iris Segmentation using the GST

$$I_{20} = cf * \left(\frac{\partial I}{\partial x} + i \frac{\partial I}{\partial y} \right)^2$$

Finding the outer iris boundary

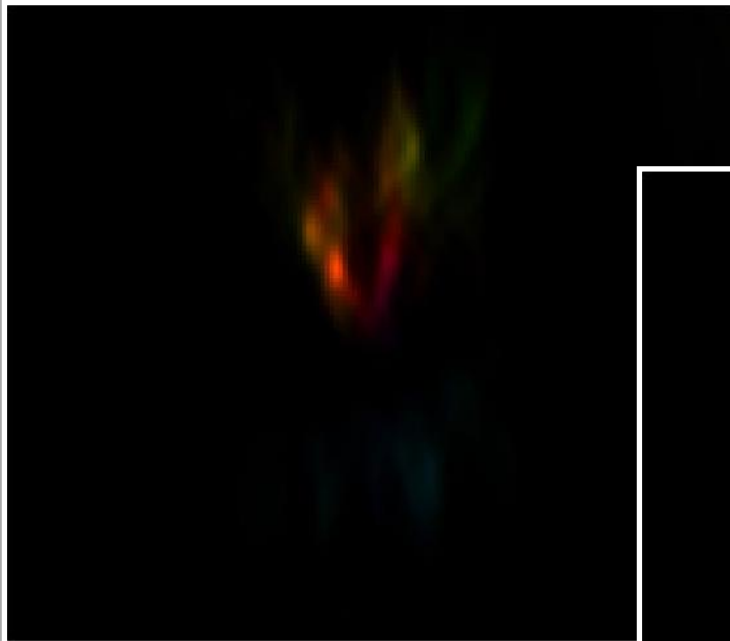


Iris Segmentation using the GST

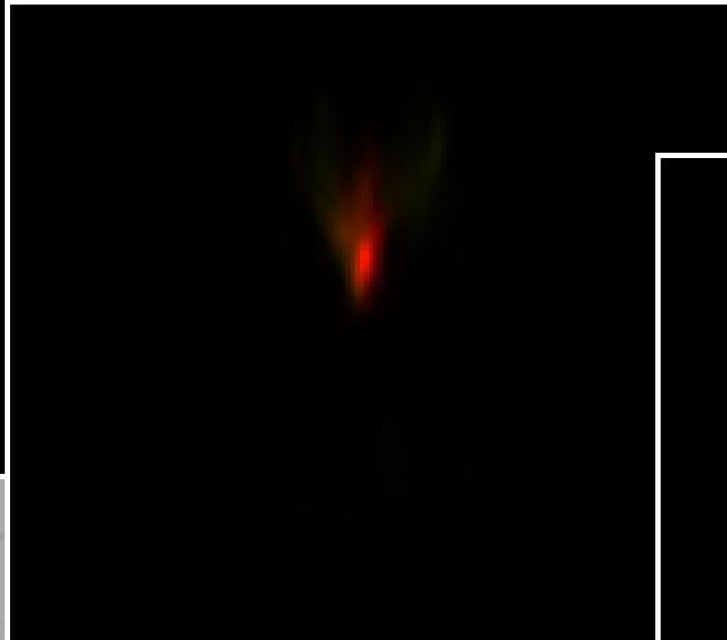
$$I_{20} = cf * \left(\frac{\partial I}{\partial x} + i \frac{\partial I}{\partial y} \right)^2$$

How filter output looks like with different filter radius...

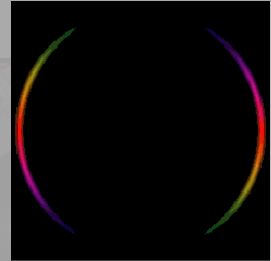
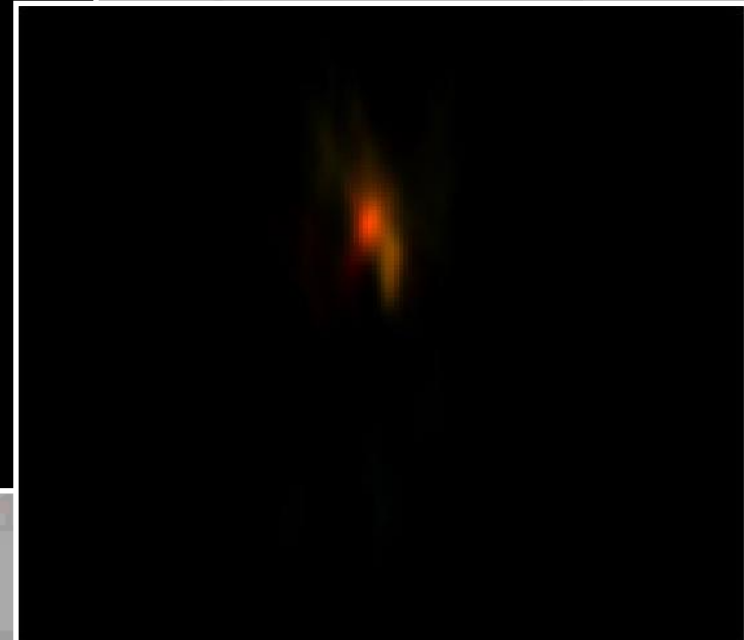
radius=100



radius=110



radius=120

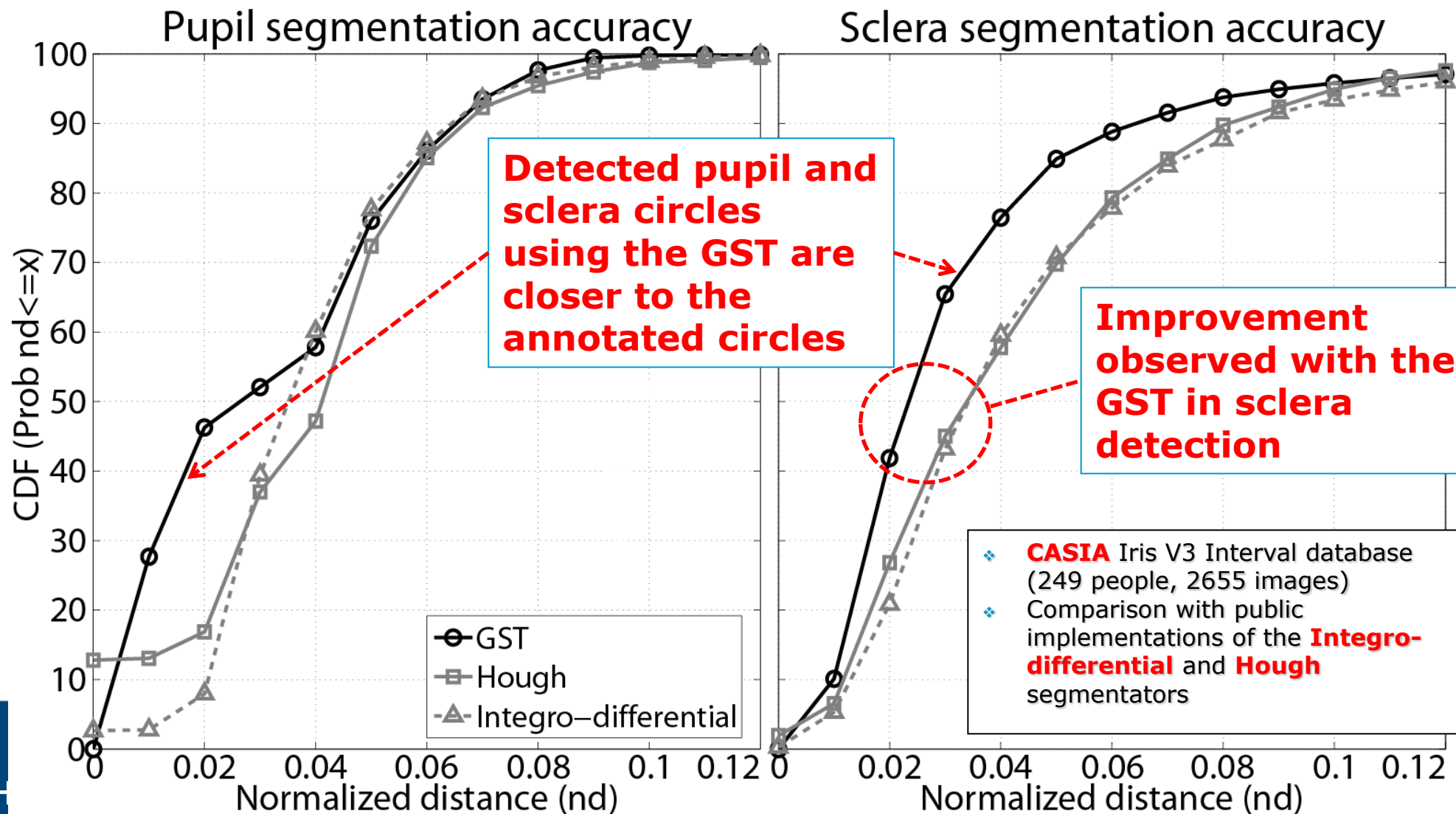


0.08
0.06

75 80 85 90 95 100 105 110

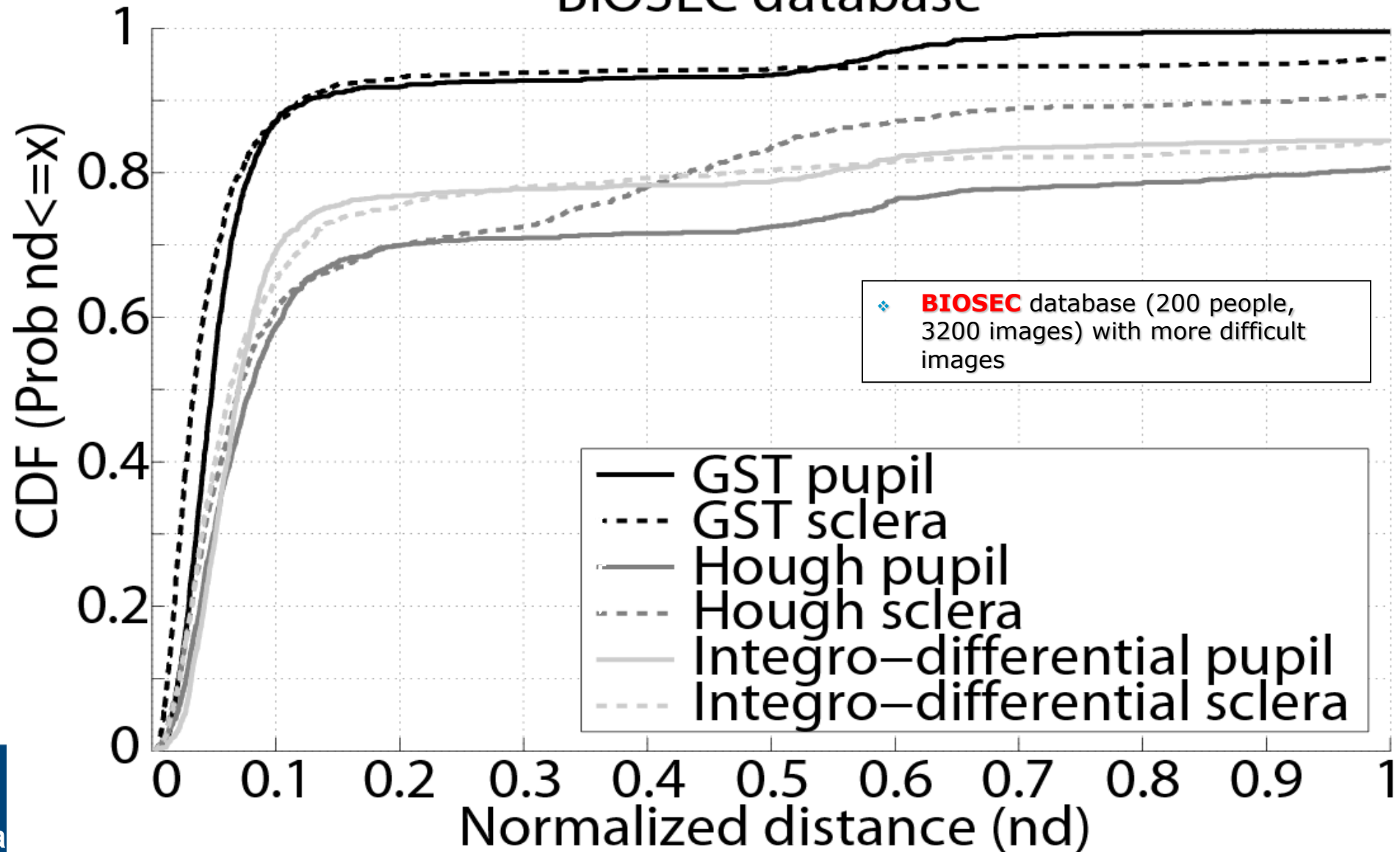
Filter radius

Iris Segmentation using the GST

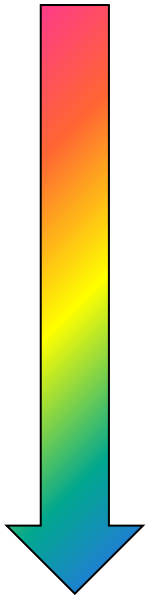


Iris Segmentation using the GST

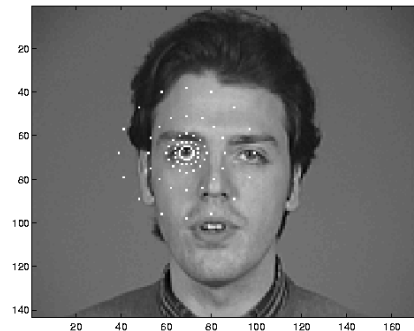
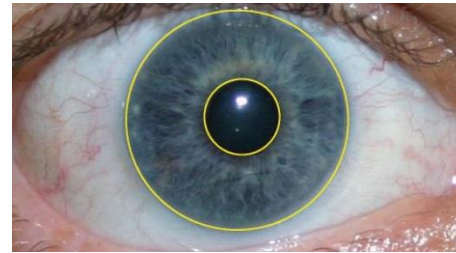
BIOSEC database



Personal Recognition based on Facial Information



- Iris Analysis
- **Periocular Analysis**
- Face Analysis



Periocular Analysis



Levels of facial analysis:

“Far”: whole face

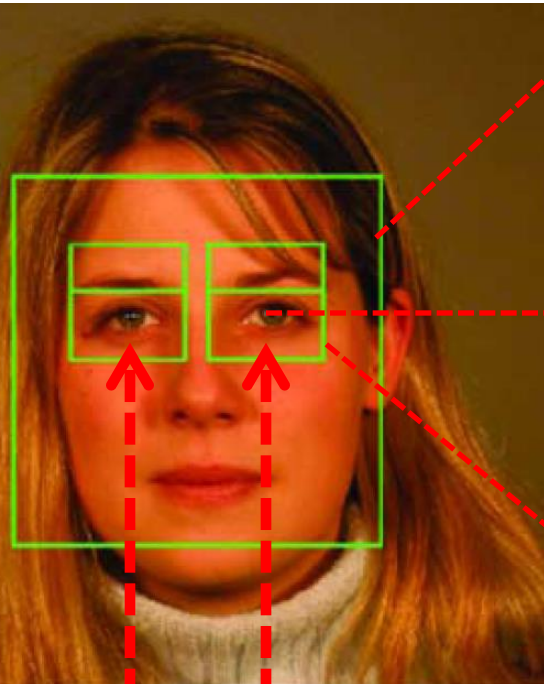
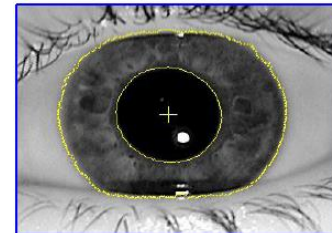
- ❑ Occlusion, lightning, background...
- ❑ Unavoidable in some applications (forensics, mobile devices...)

“Close”: iris texture

- ❑ Reliable acquisition (resolution, off-angle...)
- ❑ Works better in NIR range

“Medium”: periocular

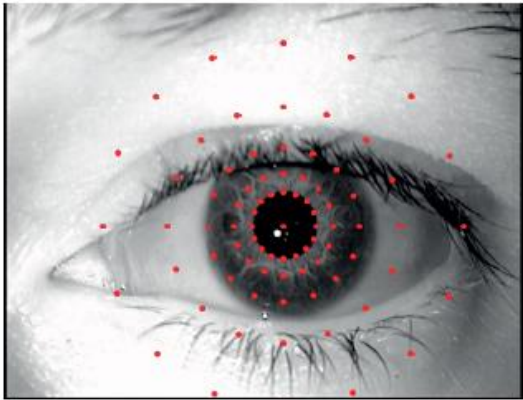
- ❑ Available over a wide range of distances, even when the iris texture cannot be reliably obtained or under partial facial occlusion
- ❑ ...and with existing face/iris acquisition setups
- ❑ Relaxation of user cooperation
- ❑ Revived attention (mobile devices, distant acquisition, surveillance...)



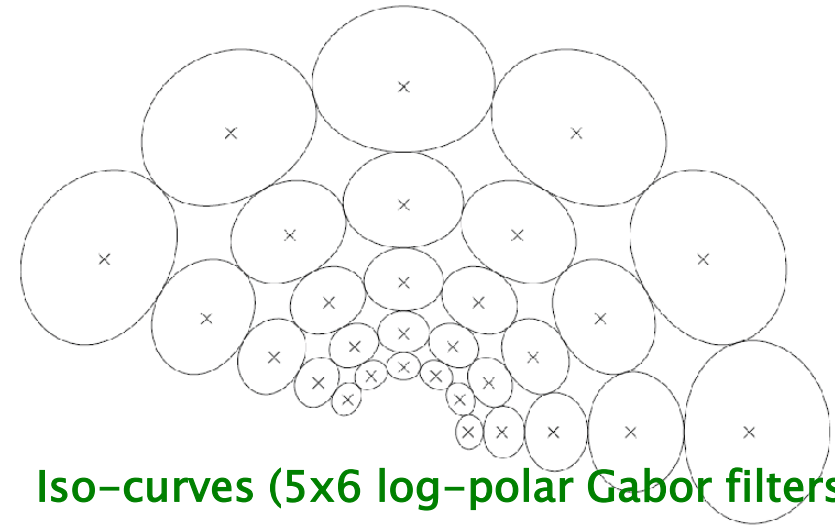
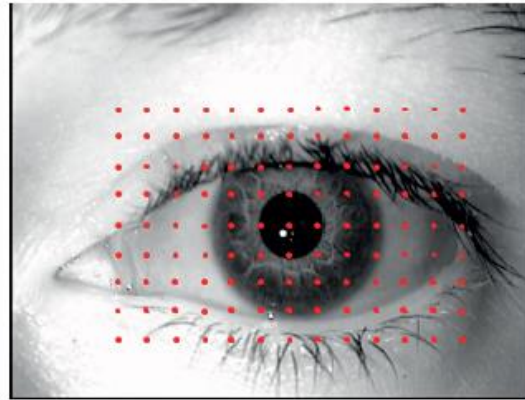
PERIOCCULAR REGION
face region in the immediate vicinity of the eye
(including eyes, eyelids, eyelashes and eyebrows)

Periocular recognition using retinotopic sampling and Gabor decomposition of the spectrum

Circular sampling



Rectangular sampling



Iso-curves (5x6 log-polar Gabor filters)

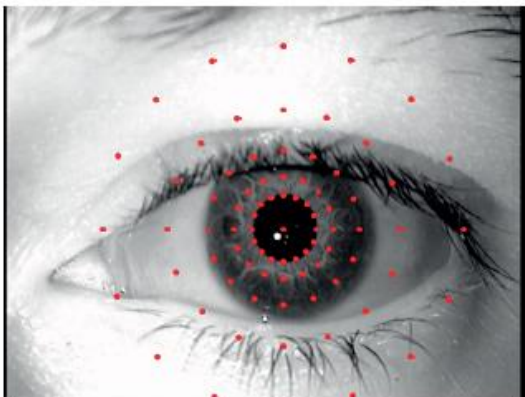
- **Databases:** CASIA (249 people, 2655 images), BioSec (200 people /3200 images)
- **Sampling grid:**
 - Circular vs. square
 - Fixed vs. variable dimensions
- **Matching using Gabor decomposition:**
 - Magnitude vs. phase information from complex responses
 - Rotation compensation between test and query images

What's in a Face?
ECCV 2012 Workshop

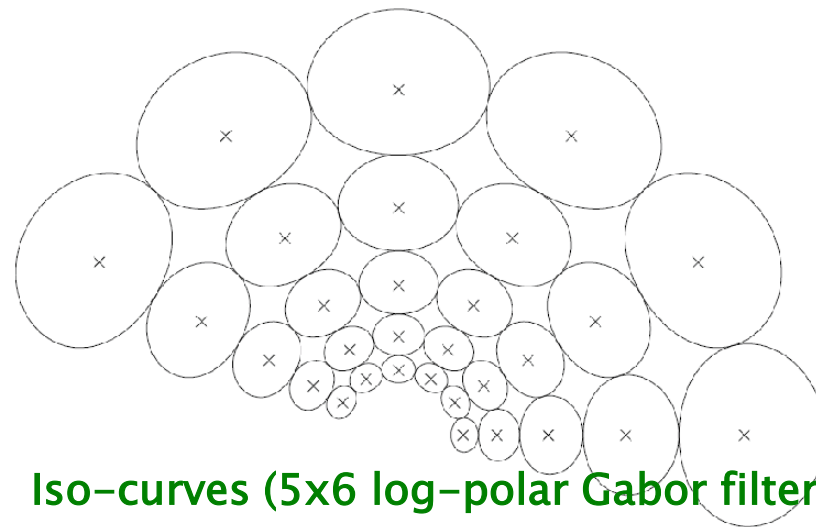
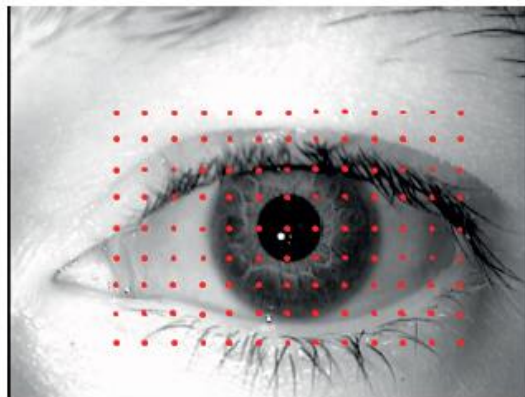


Periocular recognition using retinotopic sampling and Gabor decomposition of the spectrum

Circular sampling



Rectangular sampling



Iso-curves (5x6 log-polar Gabor filters)

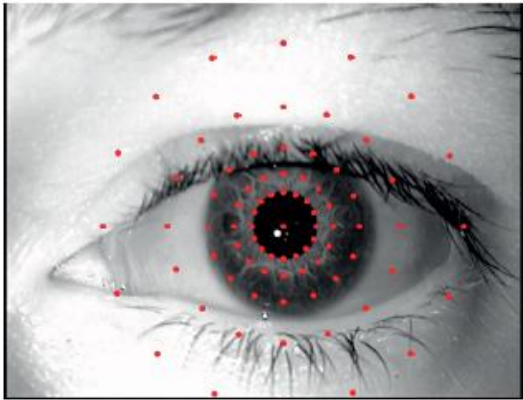
- **Best figures:** EER = 5.7% (CASIA) and 13.9% (BioSec, intersession)
- **Competitive** in comparison with results reported in the literature for other approaches:
 - LBPs: 19%
 - GO: 22%
 - SIFT: 7%

What's in a Face?
ECCV 2012 Workshop

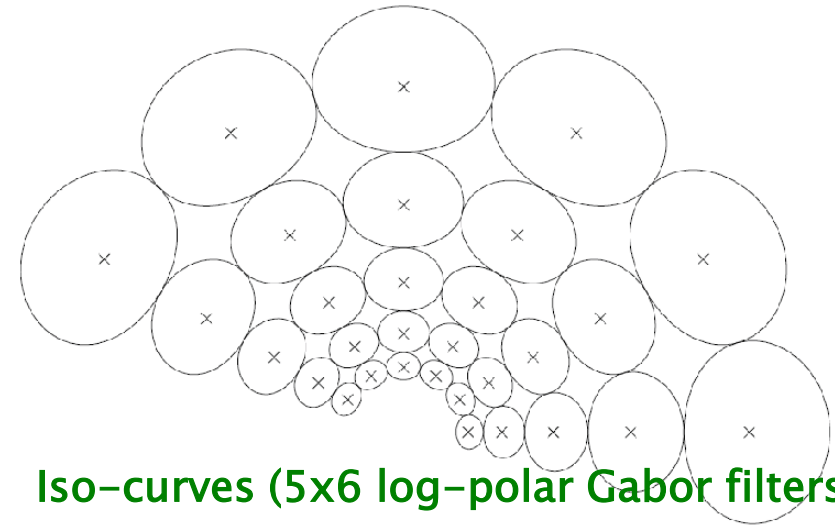
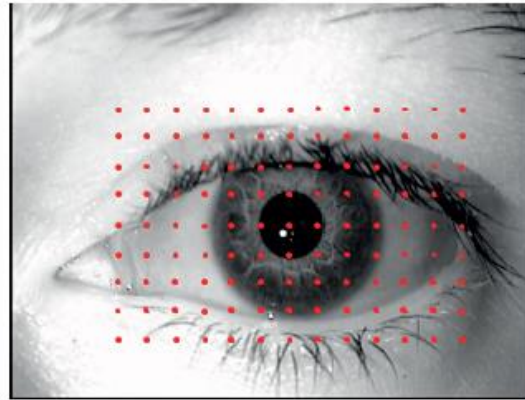


Periocular recognition using retinotopic sampling and Gabor decomposition of the spectrum

Circular sampling



Rectangular sampling



Iso-curves (5x6 log-polar Gabor filters)

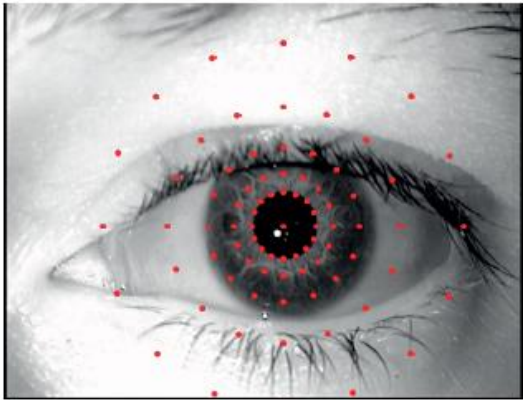
- **Other interesting outcomes:**
 - **Rotation compensation** during matching can be suppressed without sacrificing recognition accuracy
 - Performance is not substantially affected with grids of **fixed dimensions** -> no accurate iris segmentation needed, only the center of the eye

What's in a Face?
ECCV 2012 Workshop

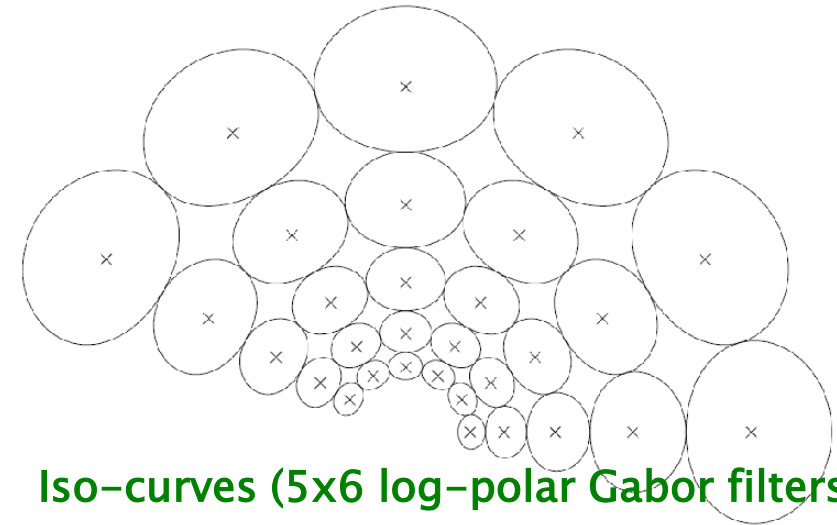
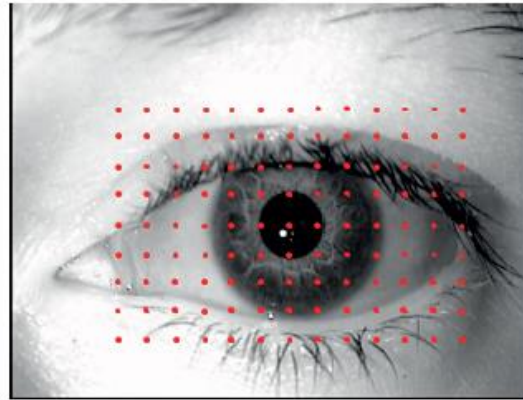


Periocular recognition using retinotopic sampling and Gabor decomposition of the spectrum

Circular sampling



Rectangular sampling



Iso-curves (5x6 log-polar Gabor filters)

- **Current directions:**
 - **Detection** of the periocular region
 - Applicability to less-constrained conditions, where **accurate detection** of the iris and/or its position is not guaranteed

What's in a Face?
ECCV 2012 Workshop



First ICB Competition on Iris Recognition



Submission based on:

- Pupil boundary detection (only) using the presented GST segmentation system
- Recognition by fusion of:
 - Periocular system described and
 - SIFT keypoints

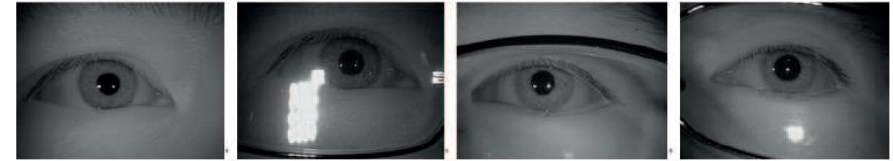


Fig. 1. Example of iris images from the ICIR2013 training database (CASIA-Iris-Thousand).

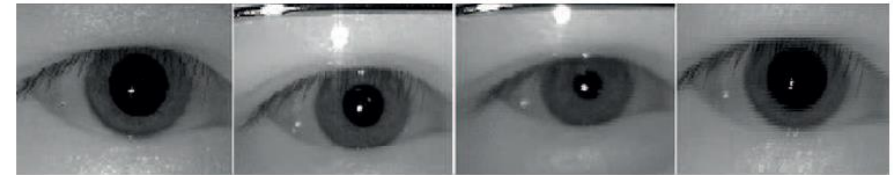


Fig. 2. Example of iris images from the ICIR2013 testing database (IR-TestV1).

Rectangular sampling

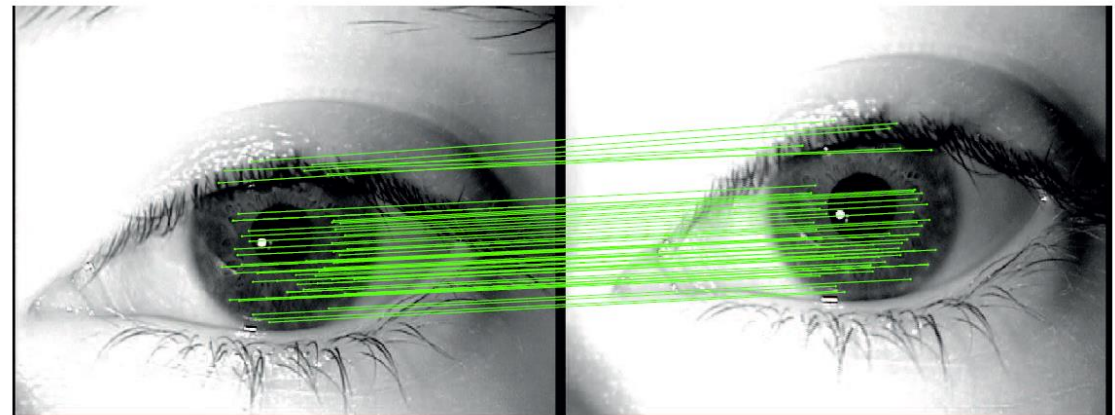
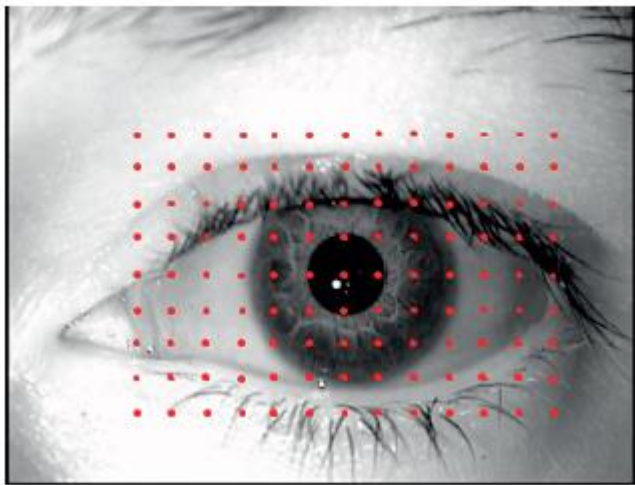


Fig. 7. Matching of two iris images using the SIFT operator.

First ICB Competition on Iris Recognition



Testing Results of The First ICB Competition on Iris Recognition (ICIR2013)

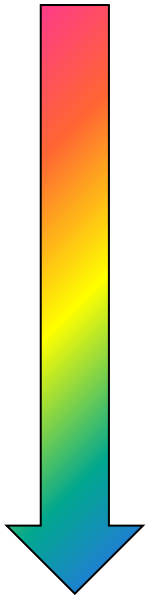
Rank	Developers	Organization	Country	FNMR@ FMR=0.0001	EER
1	Wu Su	Zhuhai YiSheng Electronics Technology Co. Ltd	China	7.09%	2.75%
2	Fernando Alonso-Fernandez Josef Bigun	University of Halmstad	Sweden	9.24%	3.19%
3	Stephane Derrode	Institut Fresnel (CNRS UMR 7149)	France	42.16%	9.33%

Number of participants: 8 developers from 6 countries

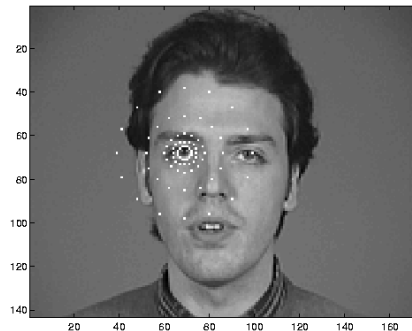
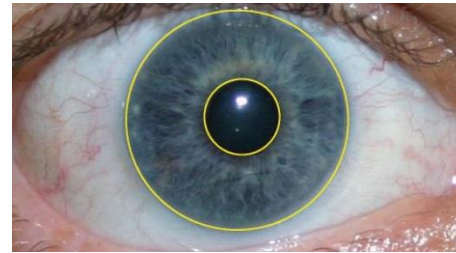
Number of algorithms: 13



Personal Recognition based on Facial Information

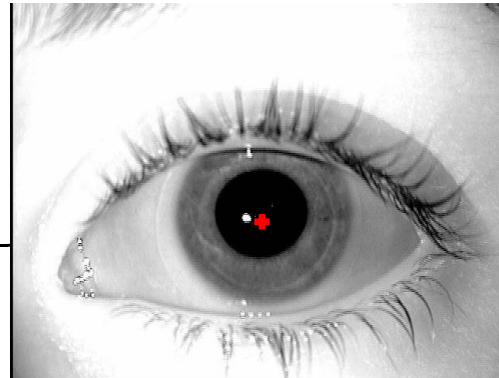
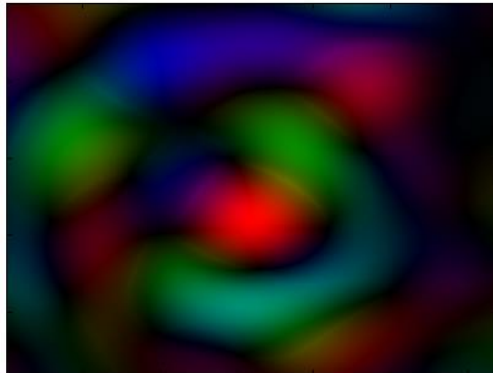
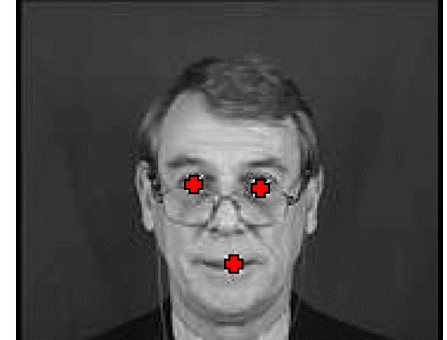
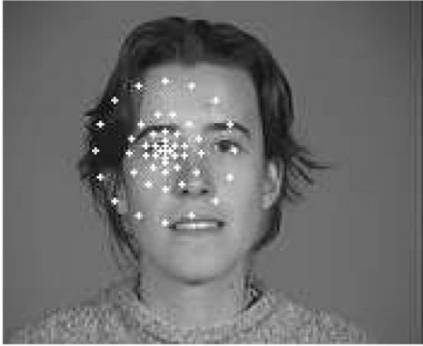


- Iris Analysis
- Periocular Analysis
- **Face Analysis**



Facial Analysis

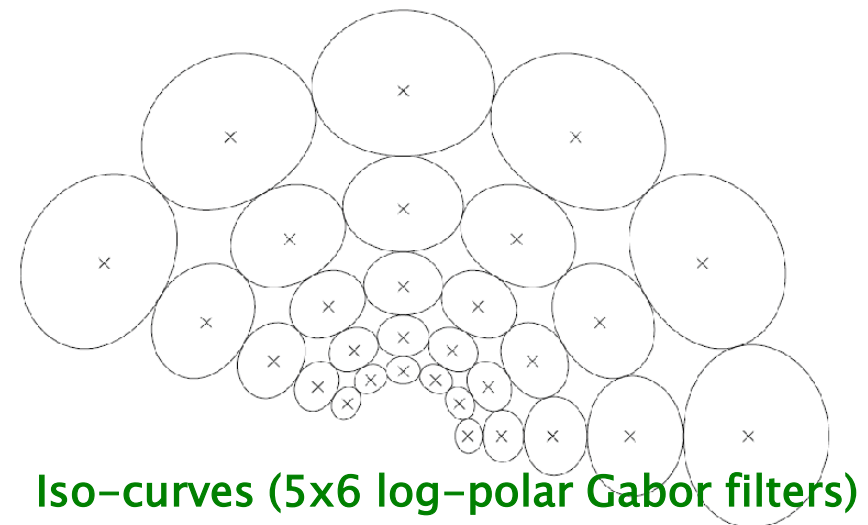
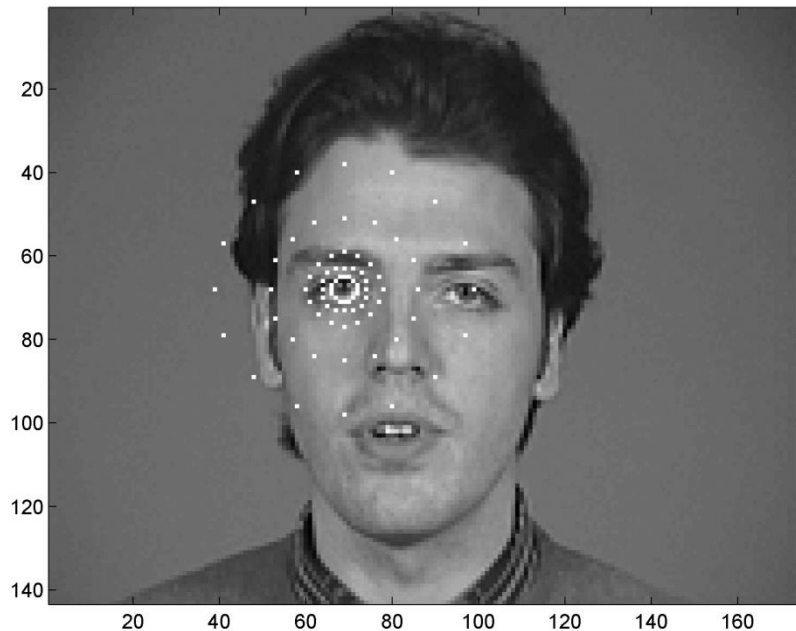
- ❑ Face and eye **detection**
- ❑ **Identity** by face



Face detection with retinotopic sampling

Local descriptors by averaging the Gabor responses from the **center** of the **eyes** and the **mouth** of a training dataset

- Vectors with orientation-selective responses for each frequency channel
- **Separate models** for each eye and the mouth

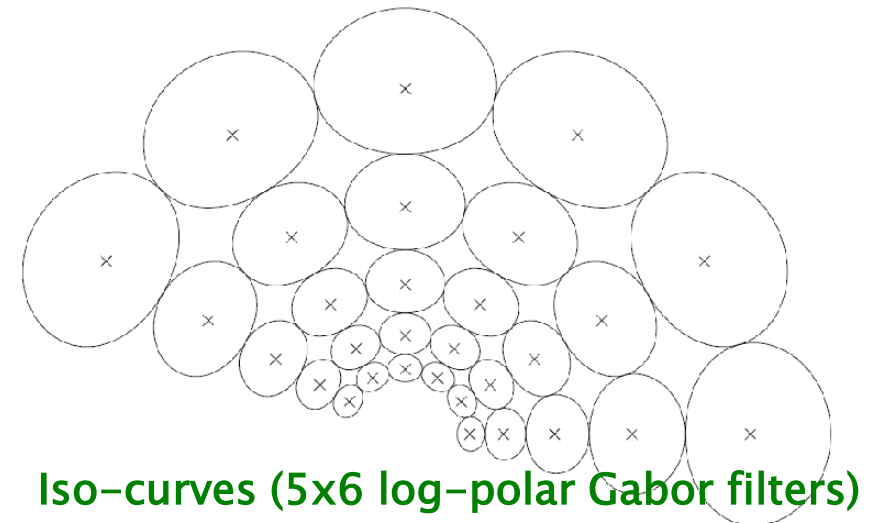
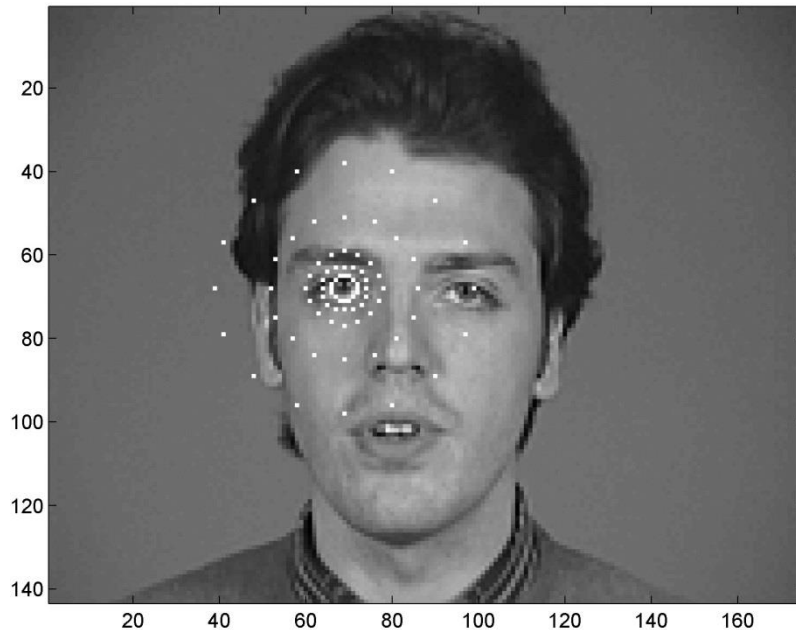


Iso-curves (5x6 log-polar Gabor filters)

Face detection with retinotopic sampling

Biological analogy of this model

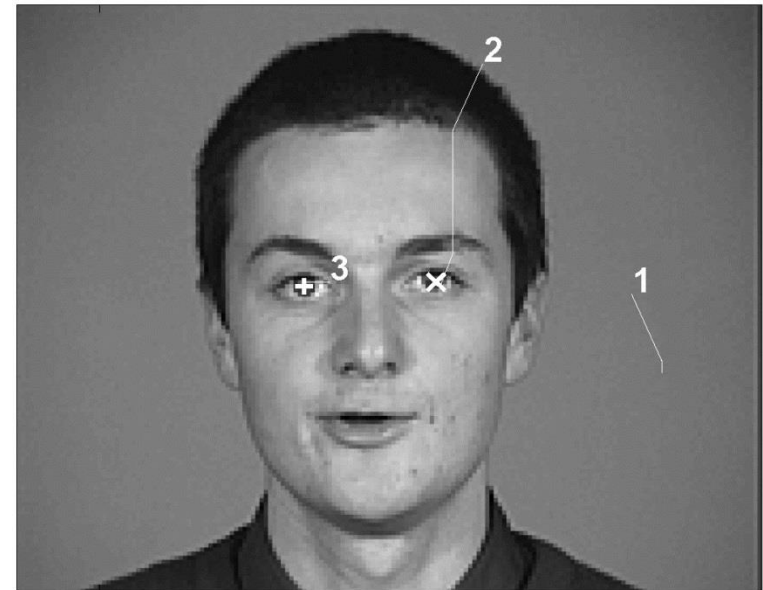
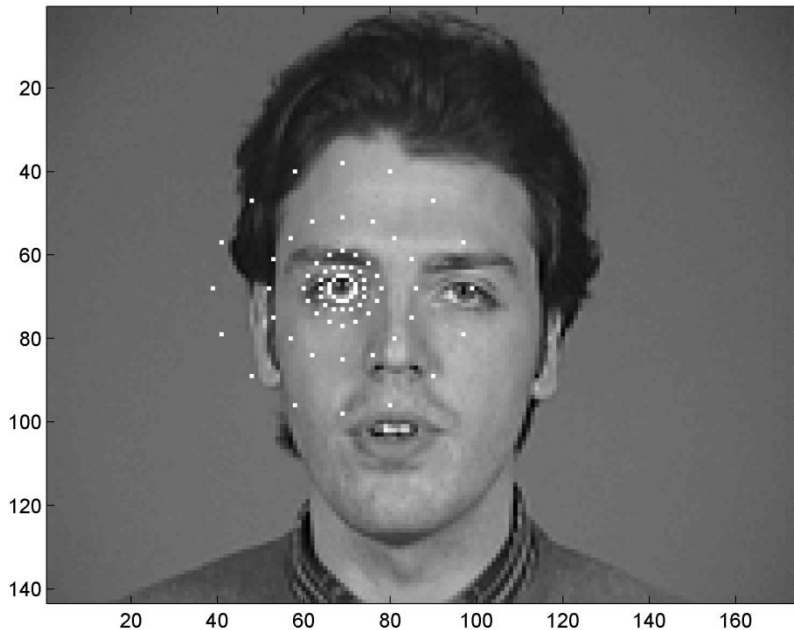
- Eyes and mouth are the main regions of interest for the brain
- Photoreceptors in the retina are arranged exponentially, with more focus of attention (~photoreceptors) in the center
- The Gabor decomposition mimics the simple cells of the primary visual cortex having the same receptive field but different spatial directions and frequencies



Face detection with retinotopic sampling

Saccadic search

- Humans do not explore the image in a raster-like fashion, instead, they perform rapid jumps (saccades) between regions of interest
- Search until convergence (maximum SVM response), which is finer as the maximum is approaching since the grid is denser at the center



Face detection with retinotopic sampling

Results with M2VTS (349 images) and XM2VTS (2388 images)

Frontal images, four sessions separated by a significant time interval

M2VTS:

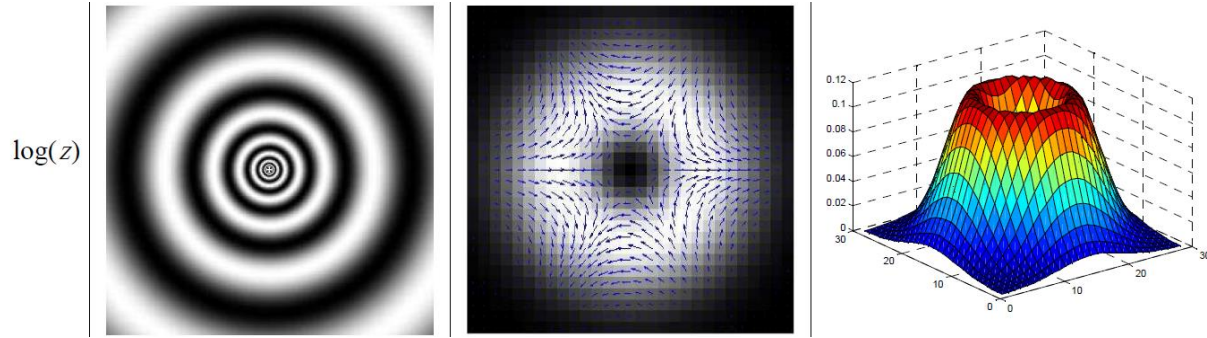
- 1.4% images: misdetection of one eye
- 98.6%: all features detected

XM2VTS:

- 0.3% images: complete erroneous detection (no landmarks detected)
- 99.5% : at least two features detected
- 97.4%: all features detected

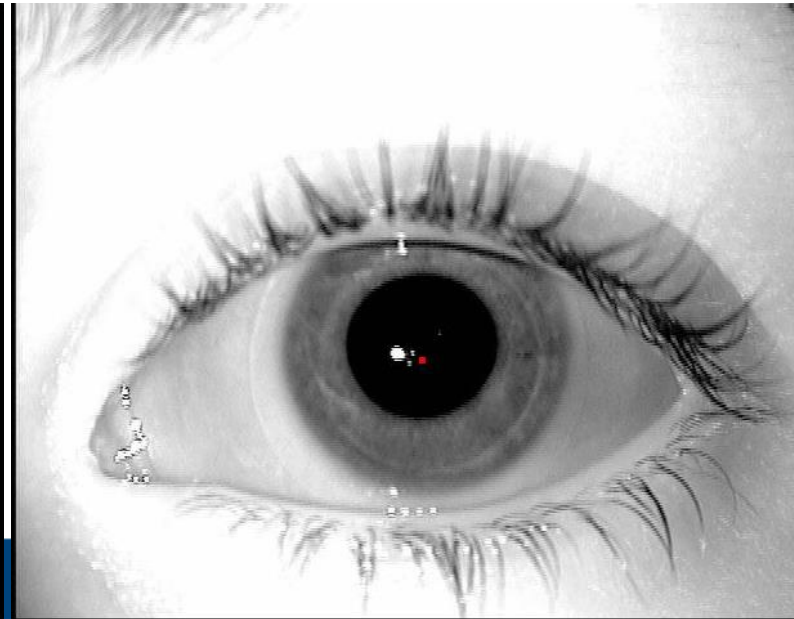
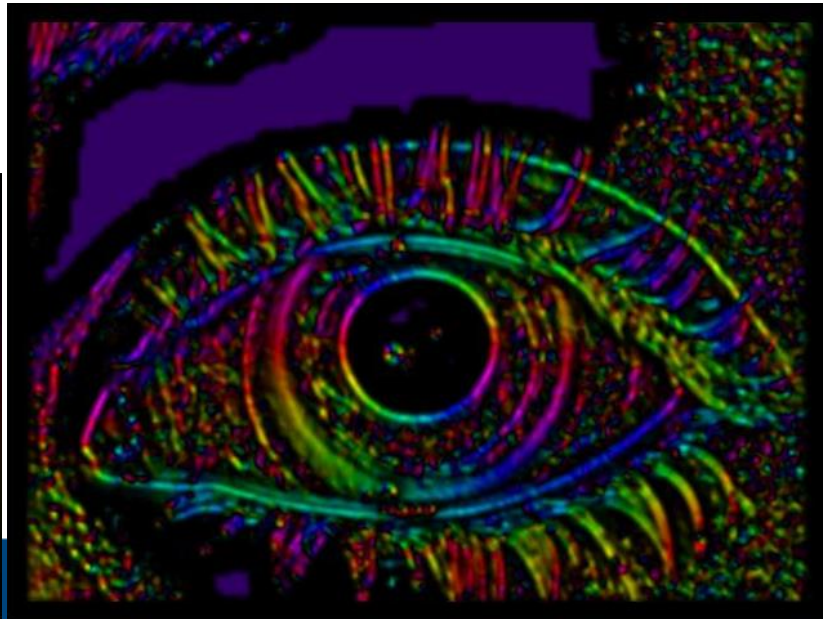


Eye detection using symmetry filters (GST)



$$I_{20} = \sum_p c[p] (f_x[p] + if_y[p])^2$$

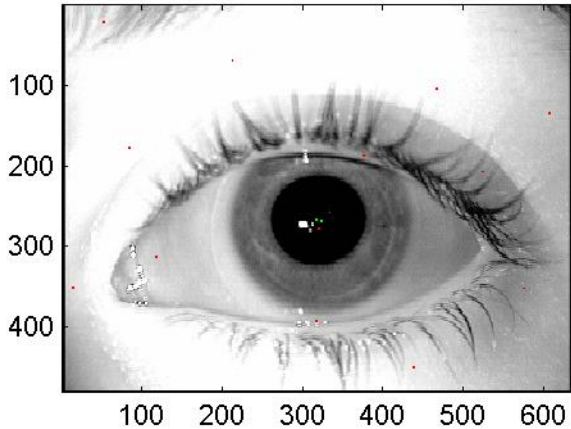
(complex)
filter



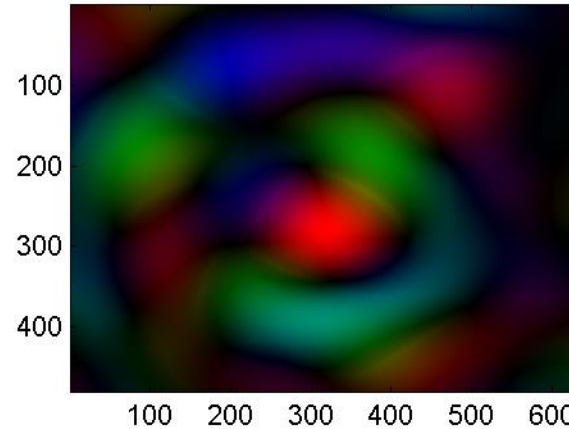
Eye detection using symmetry filters (GST)

Examples with BioSec: close-up NIR iris sensor

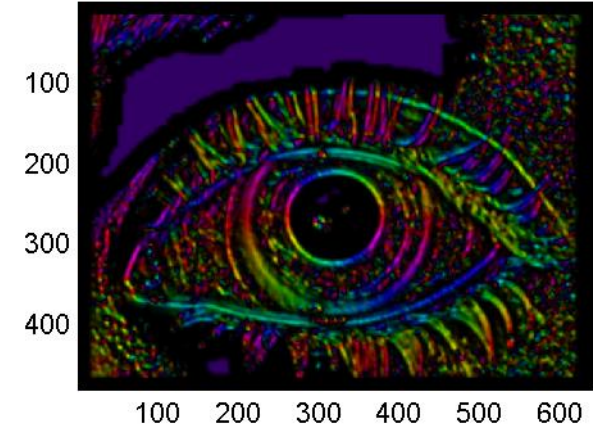
Image



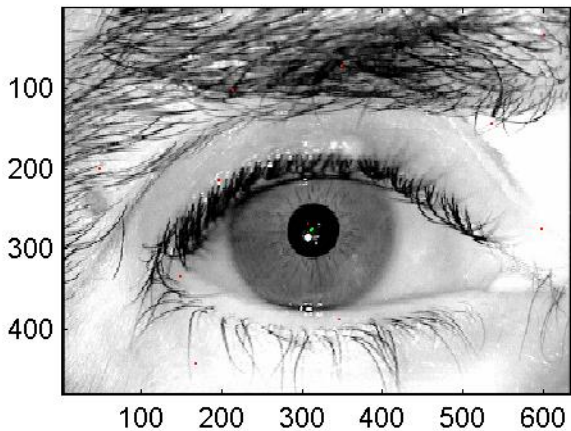
I20



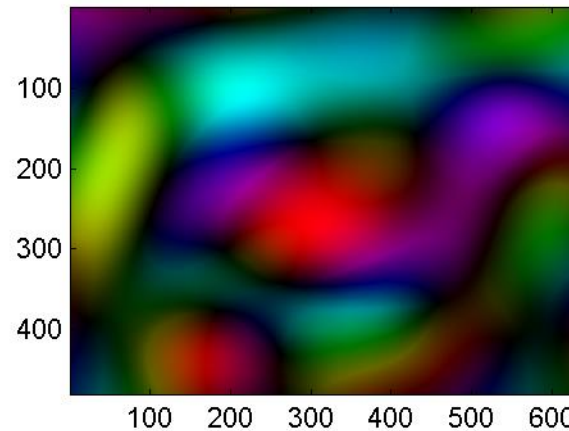
I20linear



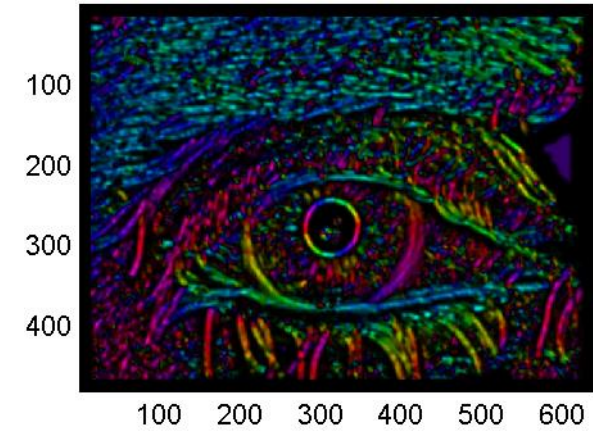
Image



I20

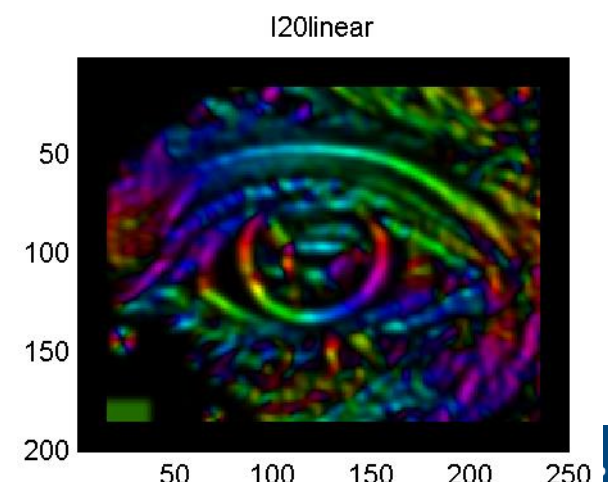
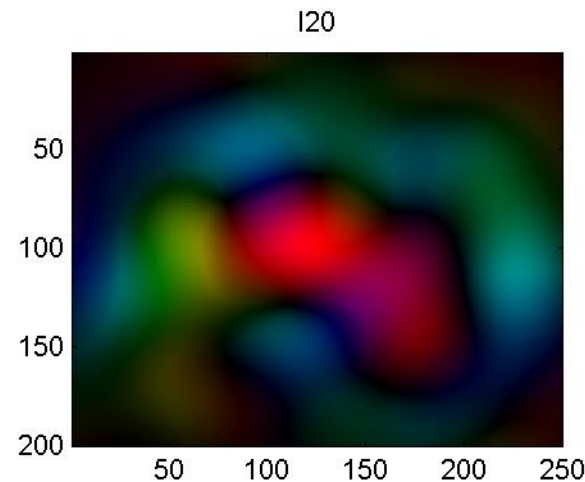
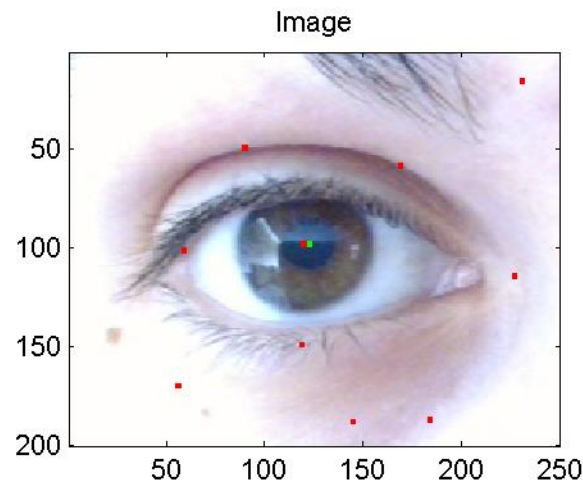
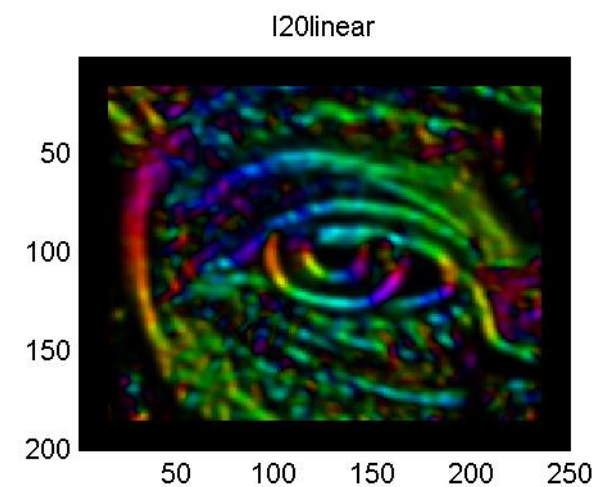
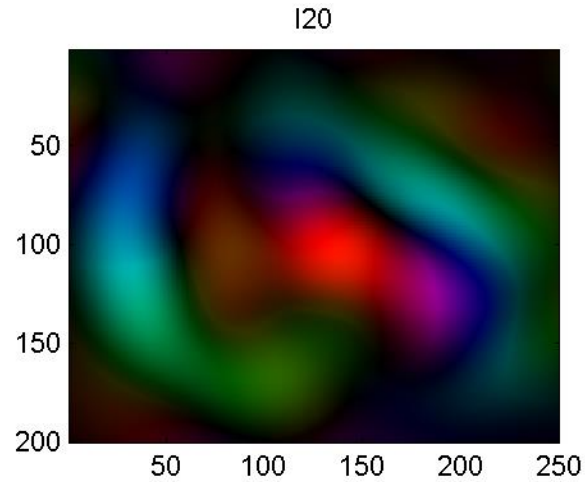
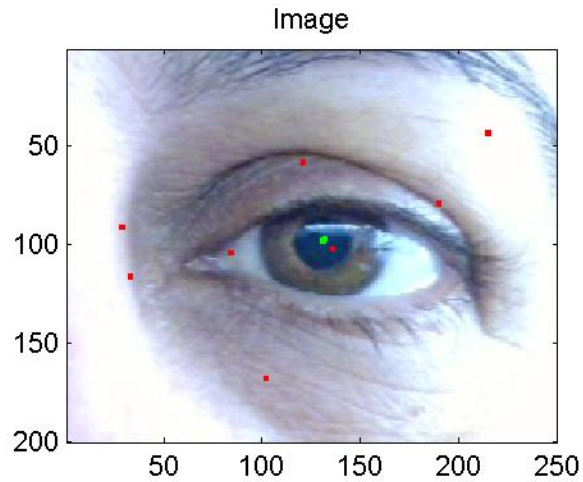


I20linear



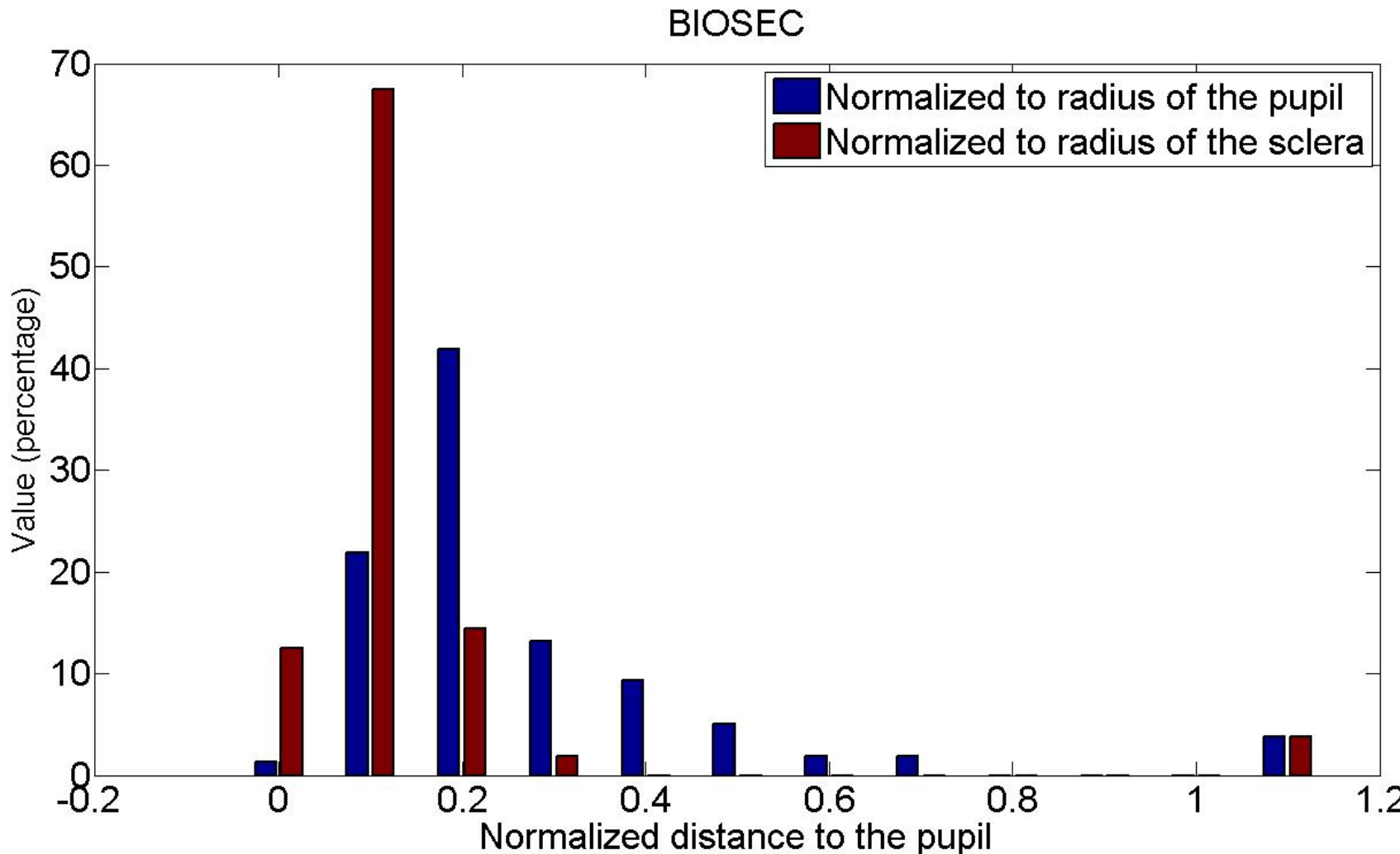
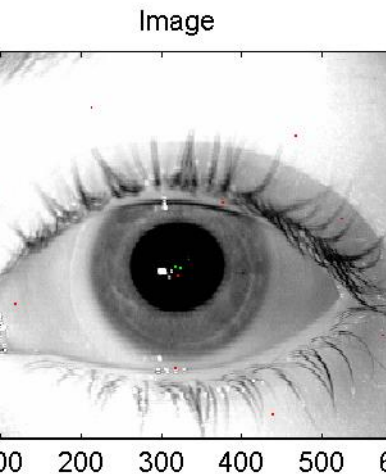
Eye detection using symmetry filters (GST)

Results with MobBIO: tablet PC webcam (visible range)



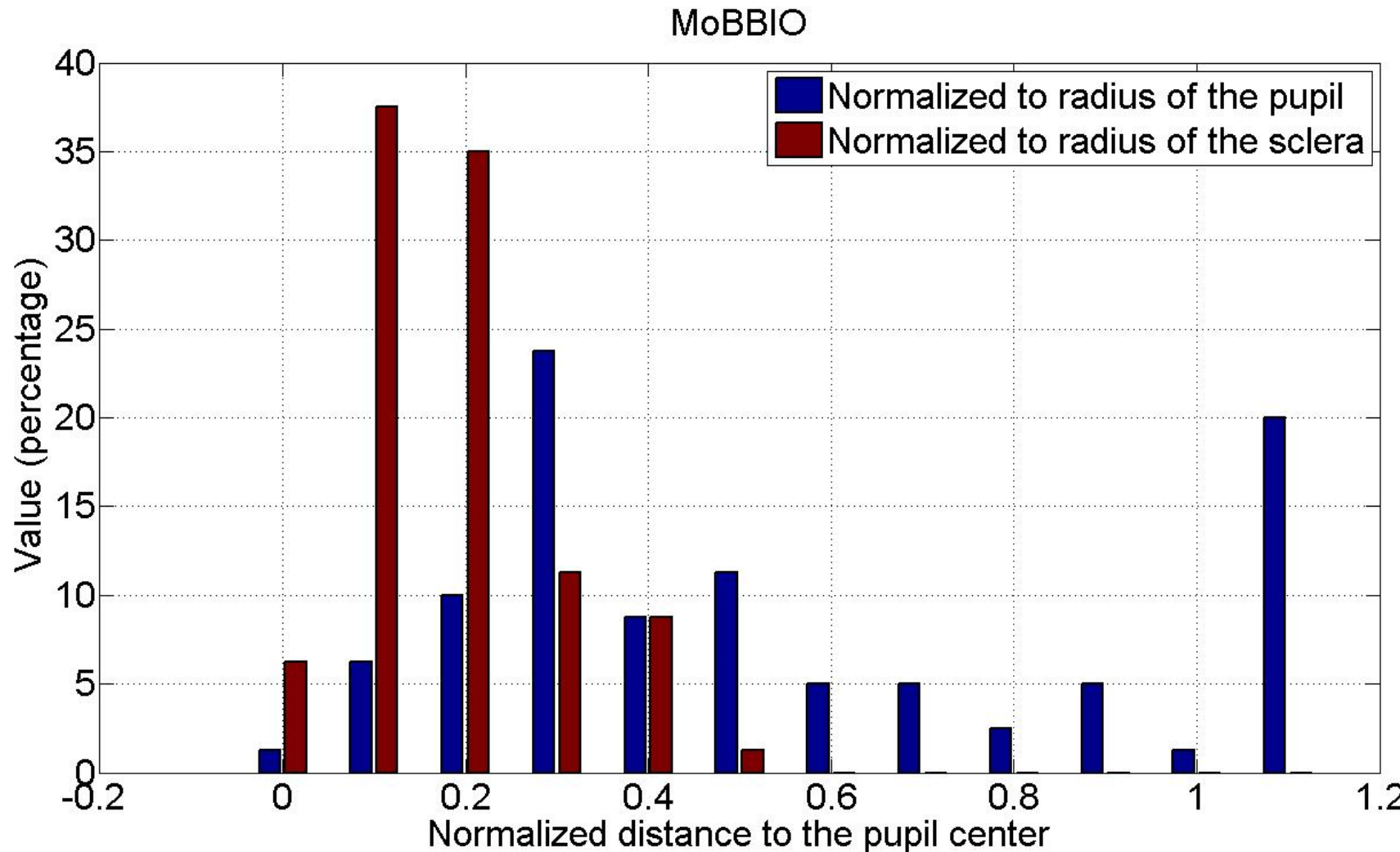
Eye detection using symmetry filters (GST)

Results with BioSec (160 images): close-up NIR iris sensor



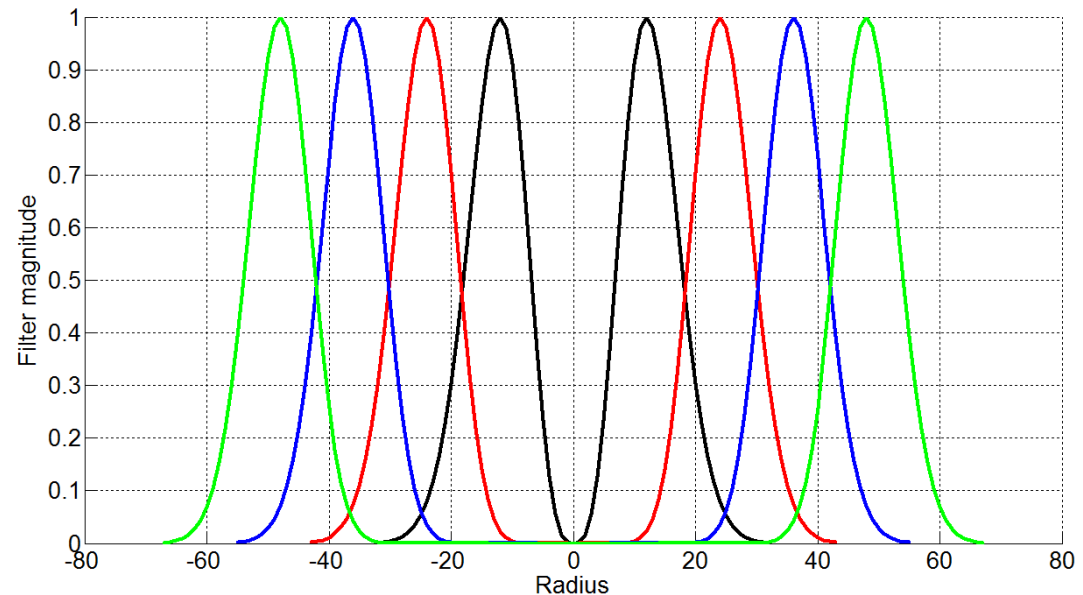
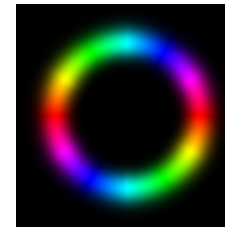
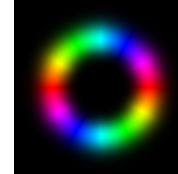
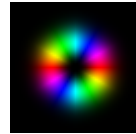
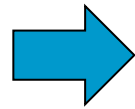
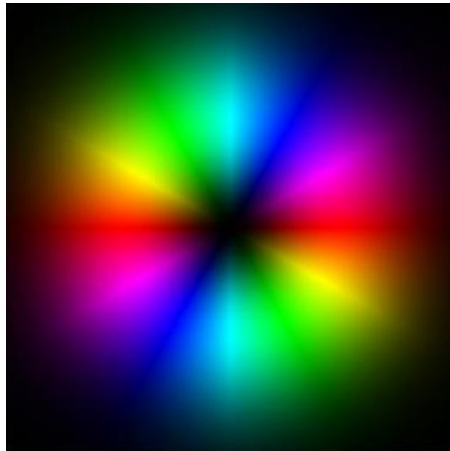
Eye detection using symmetry filters (GST)

Results with MoBBIO (80 images): tablet PC webcam (visible range)



Eye detection using symmetry filters (GST)

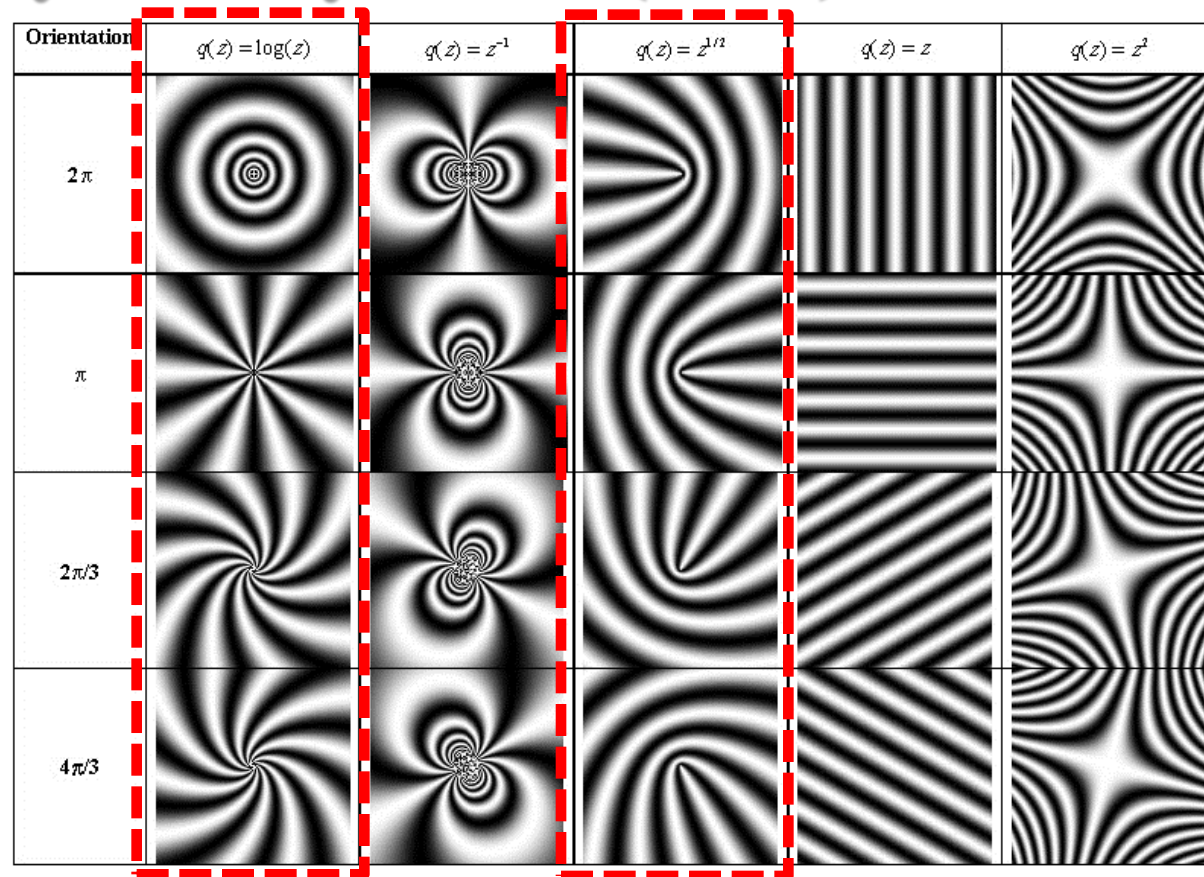
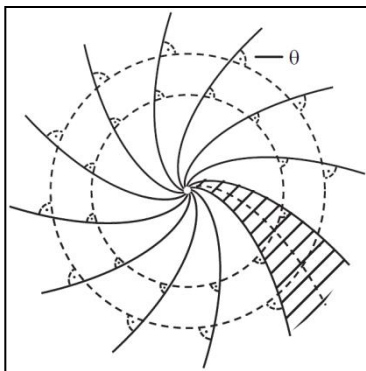
On-going work: improving the selectivity of the filter with sub-bands



Face detection using symmetry filters (GST)

On-going work:

- use other families of symmetry filters resilient to different perturbations
- use full face images and detect other landmarks (nose, mouth)... separately
- use less-constrained images (low cost devices, difficult environment)



Rotation and scale invariant

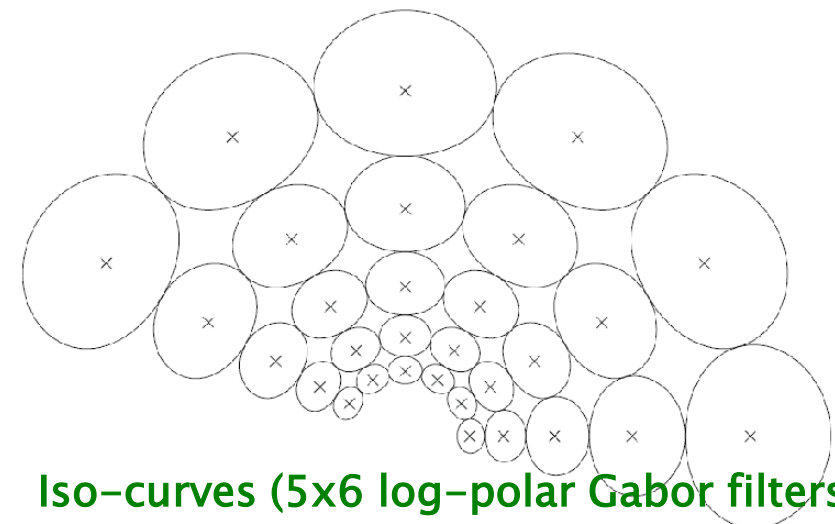
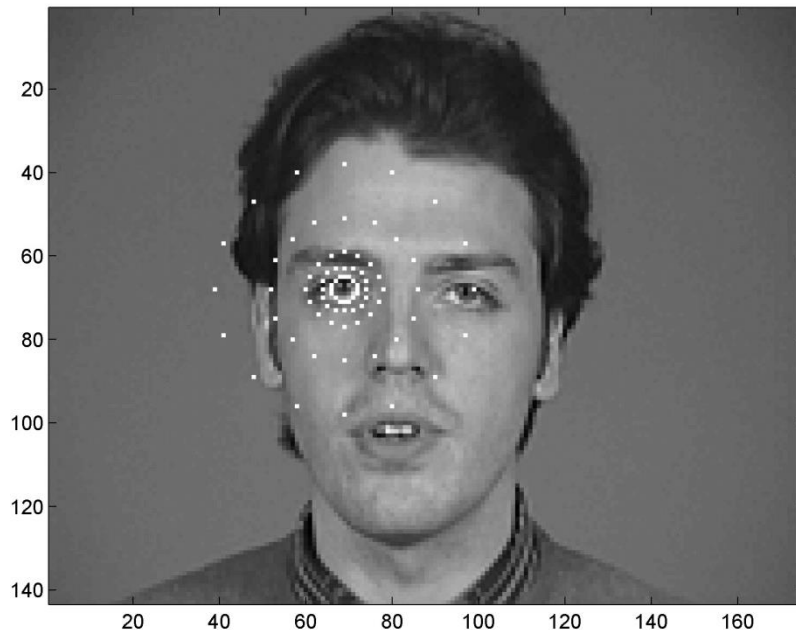
Maintains its appearance under scale and in-depth rotations



Face recognition using retinotopic sampling and Gabor decomposition of the spectrum

Same framework as presented for periocular recognition

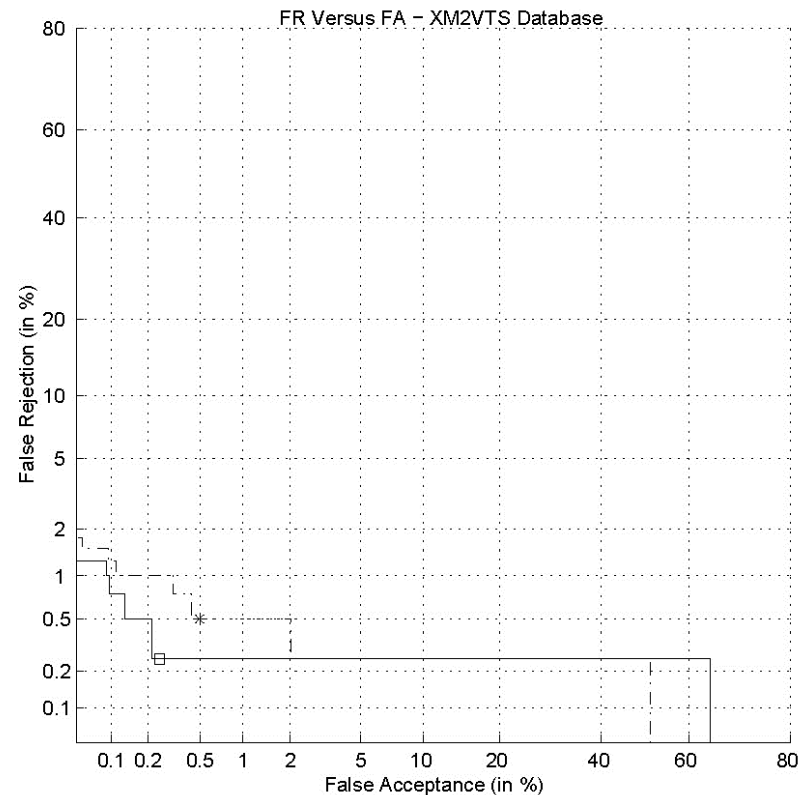
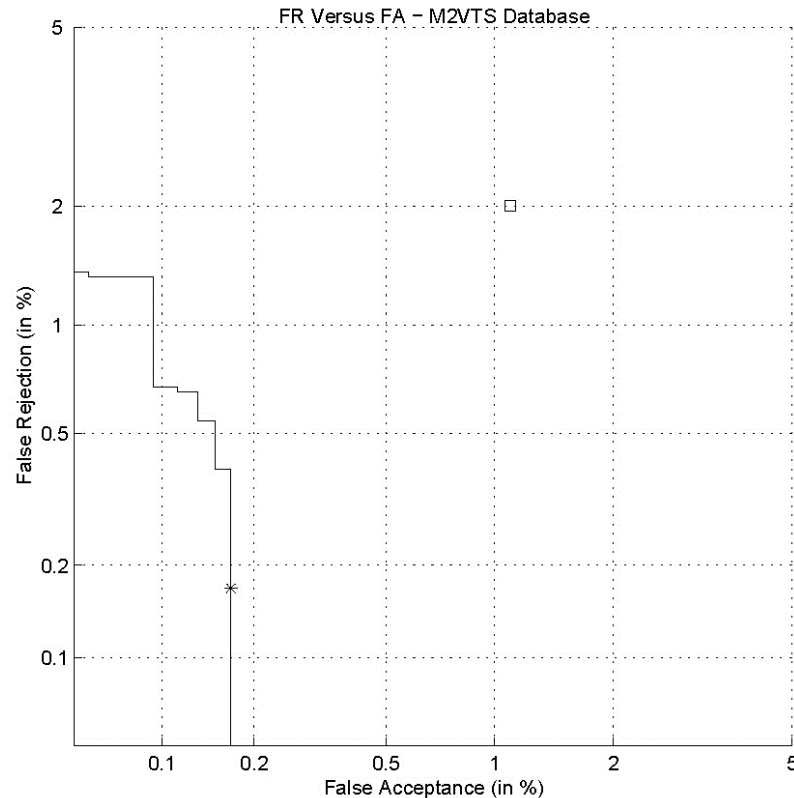
- Three classifiers based on Gabor responses with the grid on the eyes and the mouth (tested NN, KNN and SVM)
- Expert fusion of the three classifiers



Face recognition using retinotopic sampling and Gabor decomposition of the spectrum

Results with M2VTS (349 images) and XM2VTS (2388 images)

- **M2VTS:** EER=0.15% (three images per person for training)
- **XM2VTS:** EER=0.50%/0.25% (four/six images per person for training)



Personal Recognition Based on Facial Information

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